Operational Forest Mapping Systems

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Collaborators

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- Expected future collaborator
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Objectives

Comparing and evaluating different forest mapping and monitoring algorithms and approaches through collaborative efforts among LCLUC science team members

Provide optimal solutions for implementing operational forest monitoring systems

Demonstrate the unique role of Landsat TM data in mapping and monitoring forest cover characteristics.

- Spectral, spatial, and radiometric resolutions of TM data: effectively designed for regional scale mappin
- Provide links between site, regional and global scale mapping
- One of the most reliable multispectral image data sources

Comparison and Evaluation of Forest Mapping Algorithms

Evaluation of different forest mapping/monitoring algorithms will be based on:

- Accuracy of the mapping/monitoring results
 - Overall accuracy
 - Categorical accuracy
 - Misclassification costs
- Computational/operational efficiency
 - Computational and operational resources required for classification/monitoring
- Robustness of the mapping algorithms in terms of assumptions required and technical/conceptual issues involved
 - Does the algorithm conceptually sound to be applied to multispectral remote sensing data for mapping forest characteristics?
 - What kind of technical issues are involved?
 - How robust to spectral variations caused by sensor mechanisms, atmospheric, topological effects, etc. and to noise?
 - Does the algorithm consistently produce robust results with different classification schemes, different data, and in different regions?

Test Sites

- -Changbai Mountain, Northeastern China
- Allegheny National Forest, Pennsylvania
- Oconee National Forest, Georgia
- Clarion, Pennsylvania
- Tropical, and subtropical regions (Future)

Classification Methods/Algorithms Tested

- Supervised, Unsupervised, Semisupervised Approaches
- Maximum likelihood, Decision Tree, Spectral Angle Classifiers
- ANN

Fundamental premise of the remote sensing of land cover/use: Every surface object has its own unique distribution of reflected, emitted, and absorbed radiation
The same type of surface objects show "similar" spectral response patterns

- In conventional classification algorithms, similarity is measured as "distance" and classification is based on the "nearest prototype or cluster center" rule

- ISODATA, Minimum Distance, Mahalanobis, Maximum Likelihood, Fuzzy, etc

 Decision trees, neural nets classifiers based on Hypersurfaces as Discriminants
 Patterns are classified in accordance whether they are on one side or another of a hypersurface or of a set of hyperplanes

- Similarity of patterns is still measured based on the closeness (distance) to the prototypes defined by hyperplanes

Currently all available classifiers relate "similarity" to "distance"
When we accept the fact that objects alike show approximately linearly scaled variations in spectral pattern (i.e. show similar shape of pattern), we can use "spectral angle" as a metric for measuring "similarity" in spectral shape across the spectral bands Allegheny National Forest Boundary and Compartment Locations



- Stands in a Compartment
- Tally sheet information
 Species composition
 Total basal area
 DBH, Stand age, Density, etc.







Classification result – Semi Supervised Mapping Method using Spectral Angle

Comparison

(a) Supervised Spectral Angle







Lushuihe, Changbai Mountain Area, Northeast China









Clarion, Pennsylvania







							Know	n Land Us	e/Cover								
		1	2	3	4	5	6	7	8	9	10	11	12	13	14	Row Total	User's Accuracy (%)
Classified Land Use/Cover	1 2 3 4 5 6 7 8 9 10 11 12 13 14	9	9	13	10	1 14	5	7	9	13	0	4	4	1	3	9 9 13 11 14 6 8 9 13 12 4 4 6 6	100 100 90.90 100 83.33 87.50 100 100 75.00 100 100 100 100
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Producer's Accuracy (%)		100	100	92.85	100	93.33	100	100	100	100	100	100	100	85.71	65.66		
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Future Tasks

Dec 2001-June2002

- Classifications of tropical, subtropical regions including neural net
- Address issues involved in radiometric correction
- and mosaic of adjacent scenes
- Investigating TM data resampling, scaling-up, and linking to MODIS, AVHRR

July 2002-Dec 2002

- Identify & discuss optimal operational methods involved in each classification procedure with LCLUC team members

Data preprocessing Establish classification scheme Identify & locating training sites Classification Accuracy assessment

Jan 2003-Aug 2003

- Finalize optimal operational methods involved in each classification procedure with LCLUC team members

- Publish and report final project results
- Workshop

