

Industrial forest mapping: a Landsat Spatial and Temporal Approach

Luigi Boschetti, Lian-Zhi Huo, Nuria Sanchez

Department of Natural Resources and Society, University of Idaho, Moscow, ID (USA)

Andrew Hudak

Rocky Mountain Research Station, US Forest Service, Moscow, ID USA)

Robert Keefe, Alistair Smith

Department of Forest, Rangeland and Fire Sciences, University of Idaho, Moscow, ID (USA)

Collaborators:

David Roy (SDSU, USA)

Alberto Setzer (INPE, Brazil)

Mastura Mahmud (Universiti Kebangsaan, Malaysia)

Nicola Clerici (Universidad del Rosario, Colombia)

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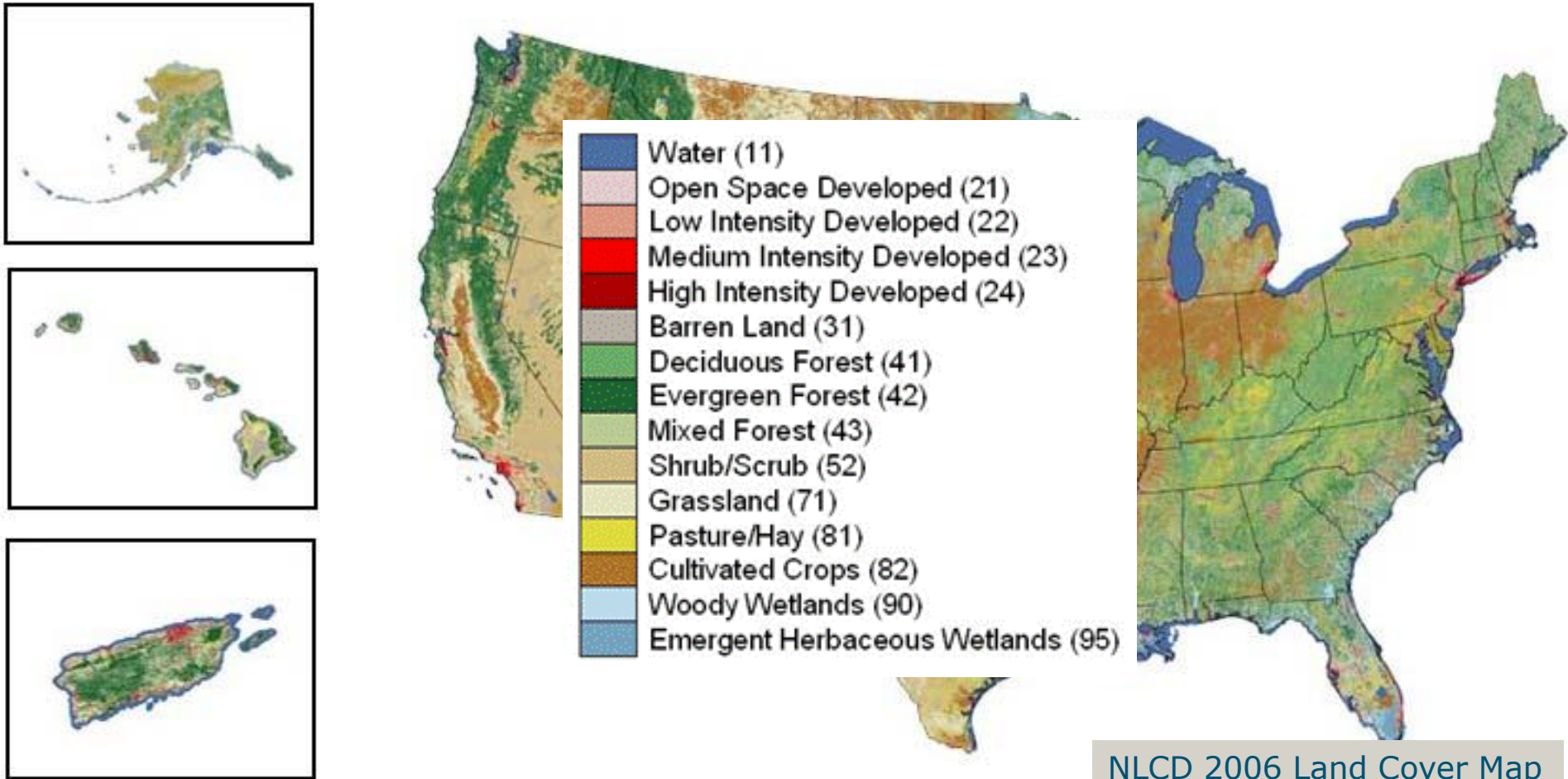
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Objective of the project

- Prototype a method for monitoring and mapping globally industrial forests, using Landsat data
- Industrial forest = forest with productive use:
 - Plantations
 - Semi-natural forests
- Study Area:
 - Wall-to-wall CONUS
 - test sites in tropics
- Tests of combined use of Landsat and LIDAR

Large RS heritage on forest



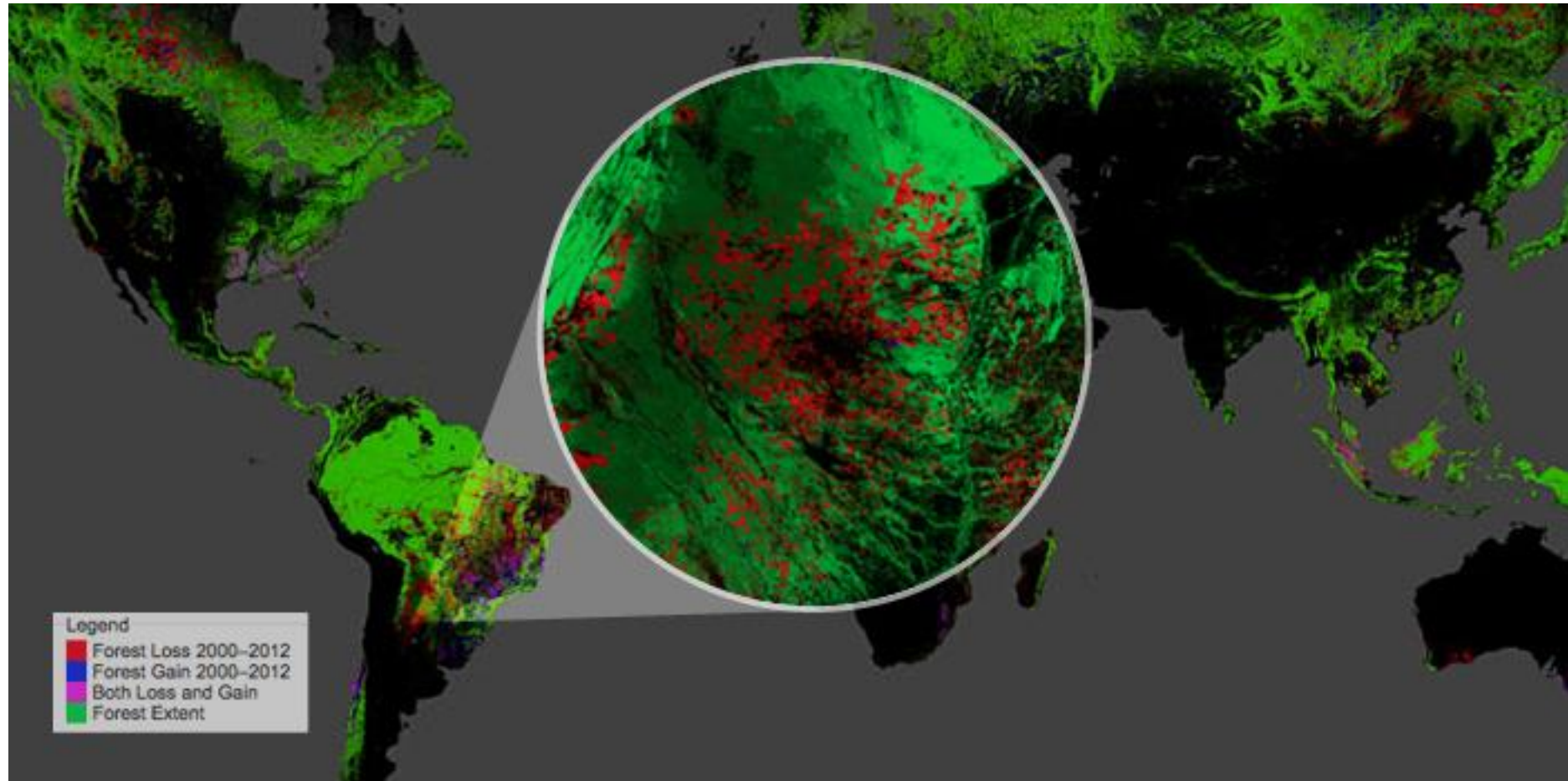
NLCD 2006 Land Cover Map

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Large RS heritage on forest monitoring



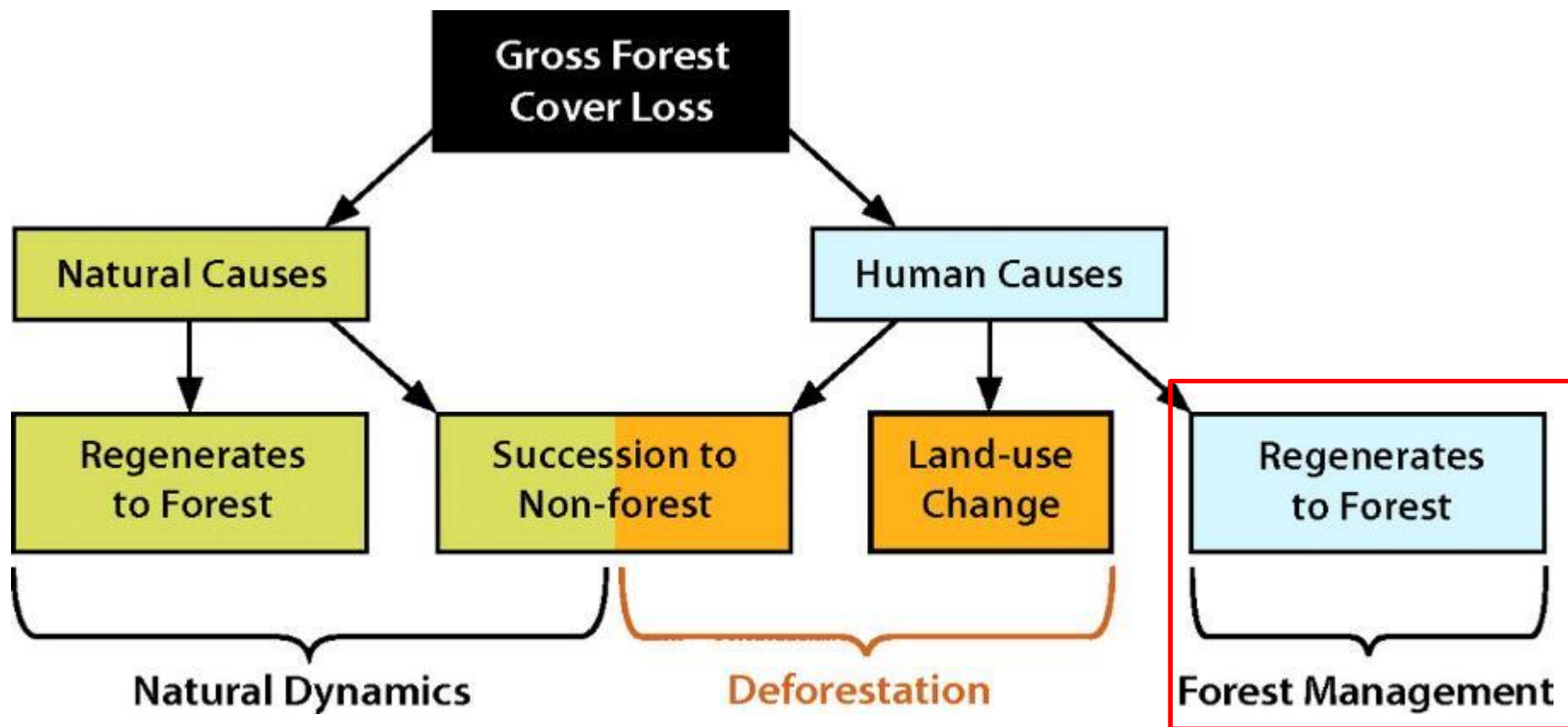
Hansen et al 2014

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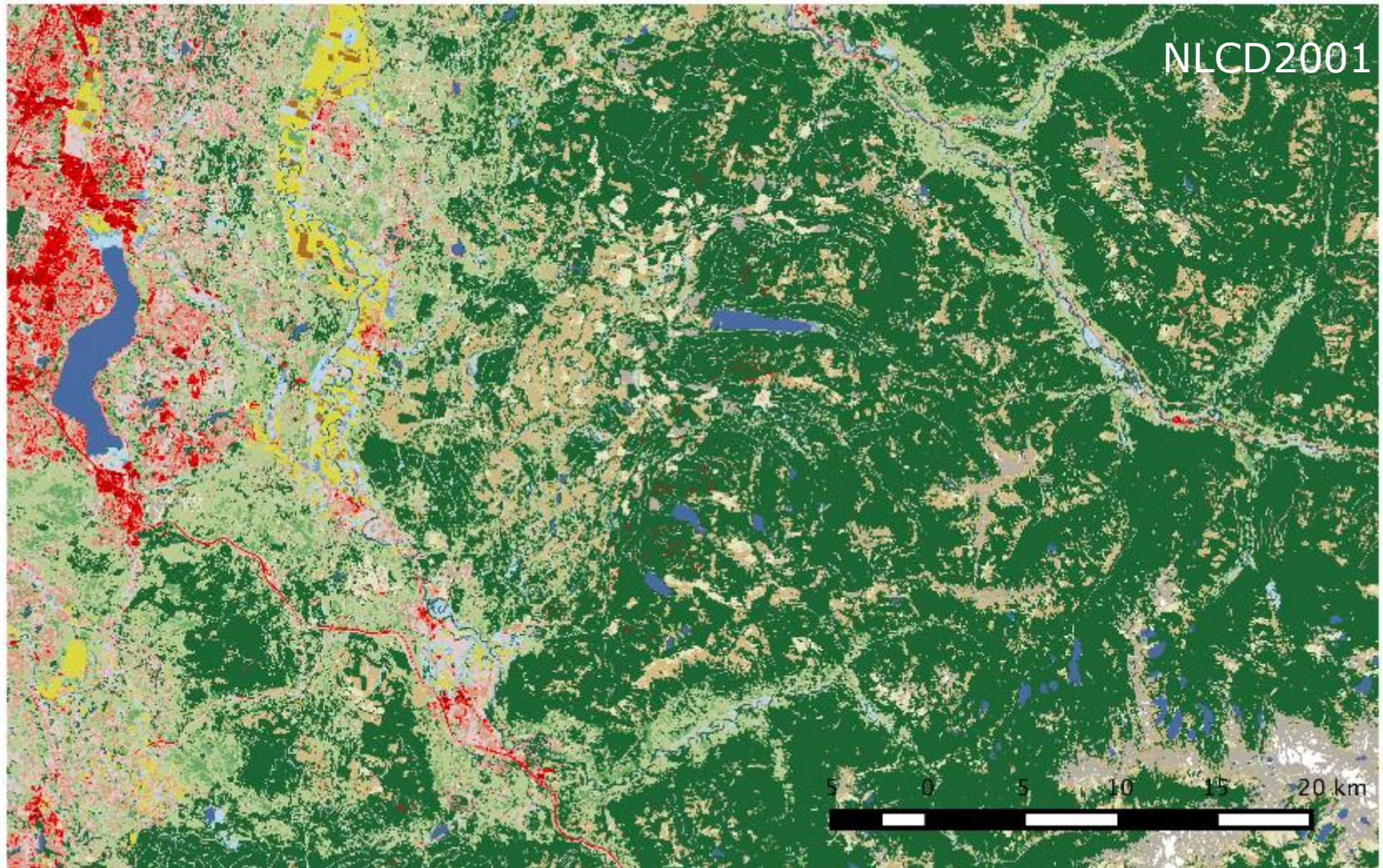


Gross Forest Cover Loss \neq Deforestation



Kurtz, 2010

Mapping Forest Land Cover \neq Land Use

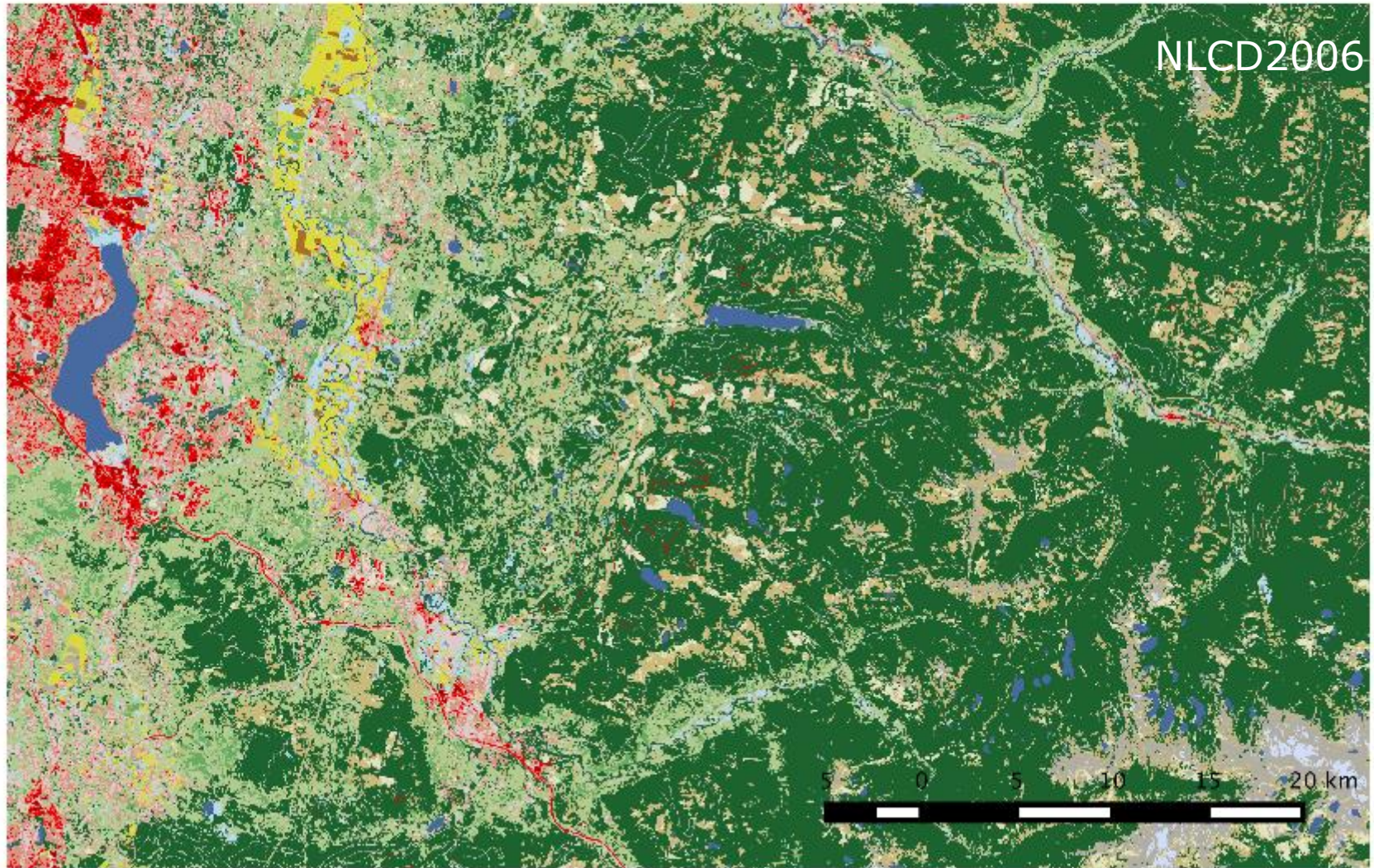


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Mapping Forest Land Cover \neq Land Use



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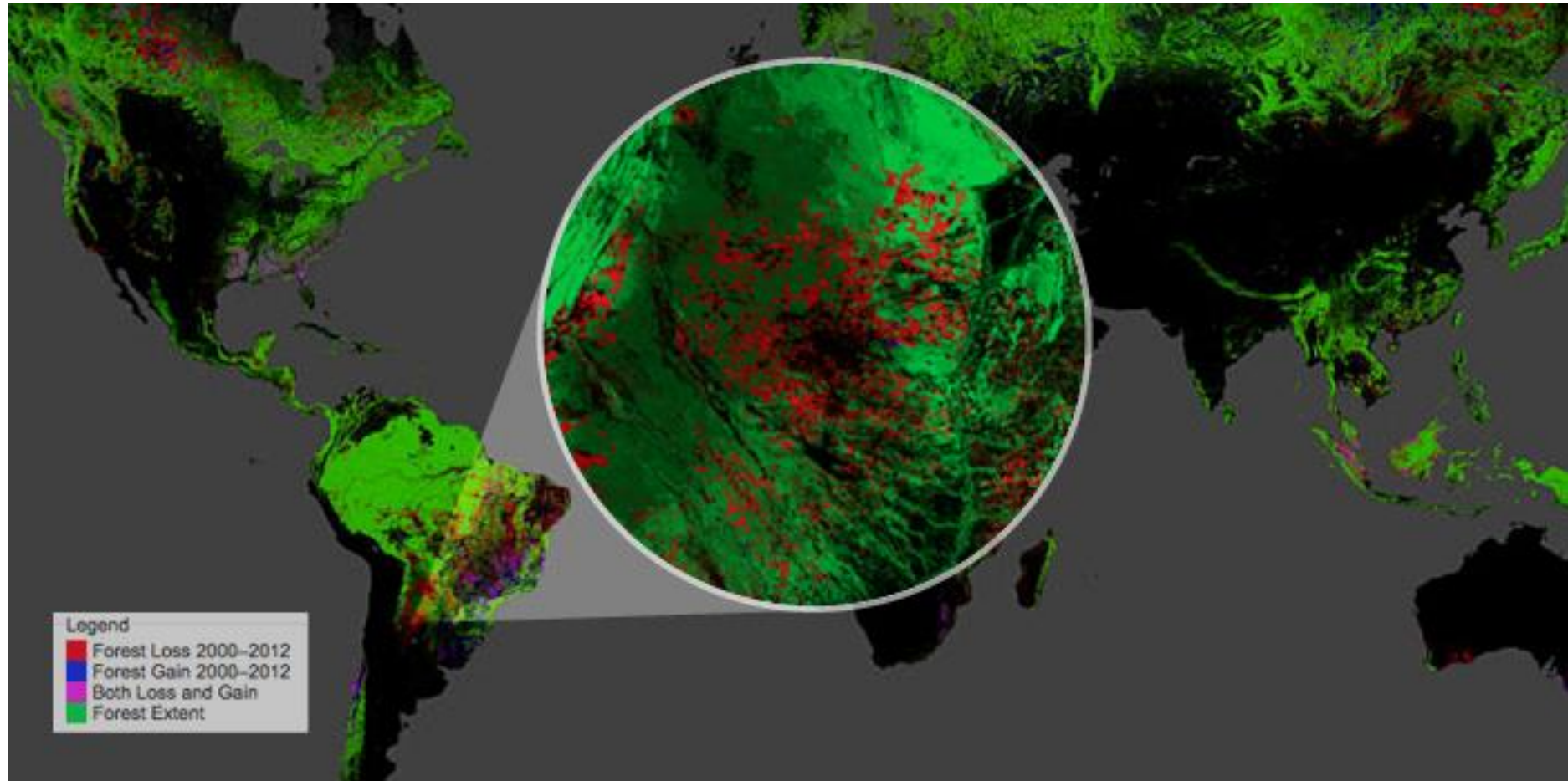
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Current project activities

1. Detecting Landsat-era forest management activity: 2003-2011 forest clearcuts in the CONUS
2. Detecting pre-Landsat forest management activities combining Lidar and Landsat data: test cases in the Pacific Northwest

Large RS heritage on forest monitoring



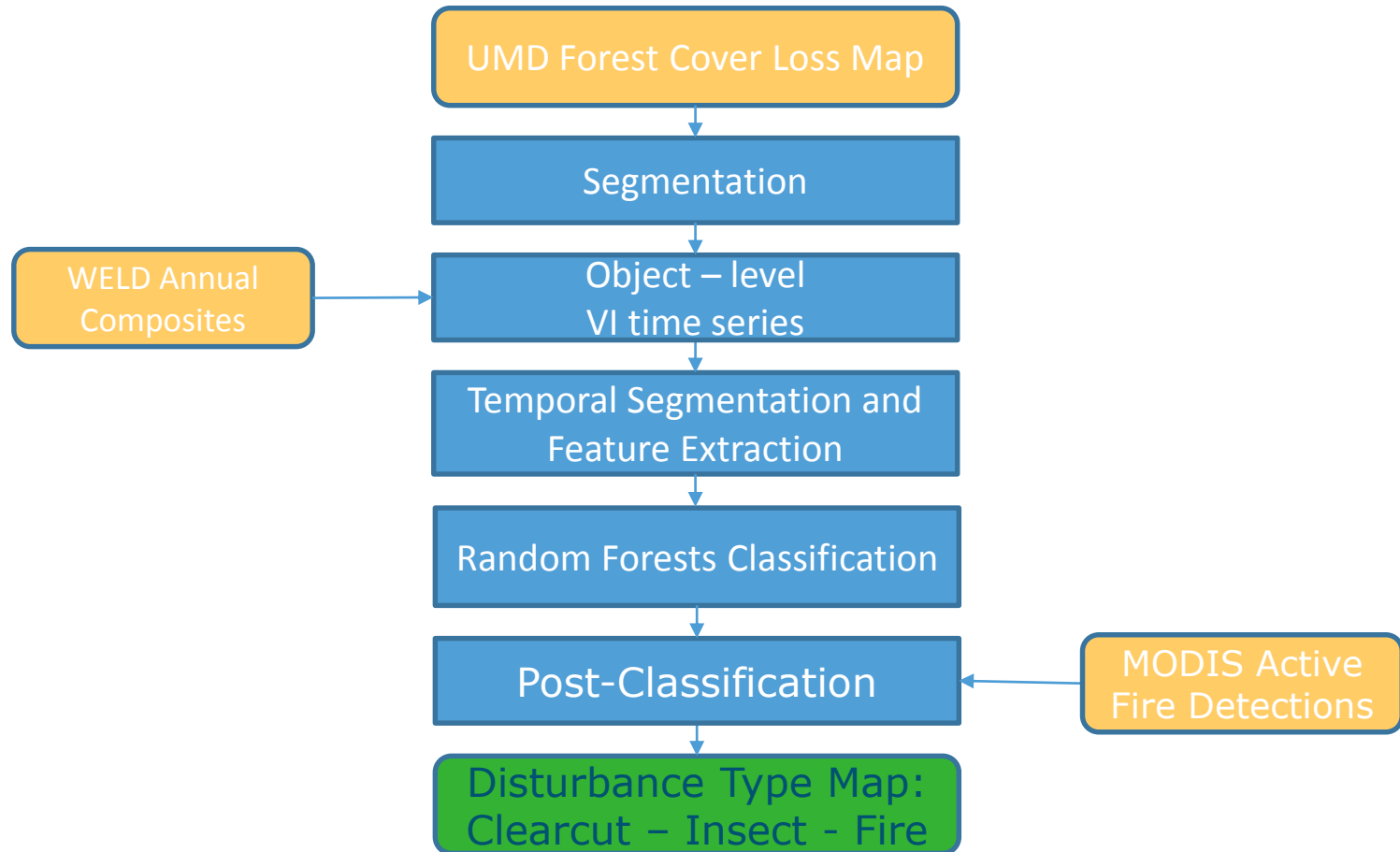
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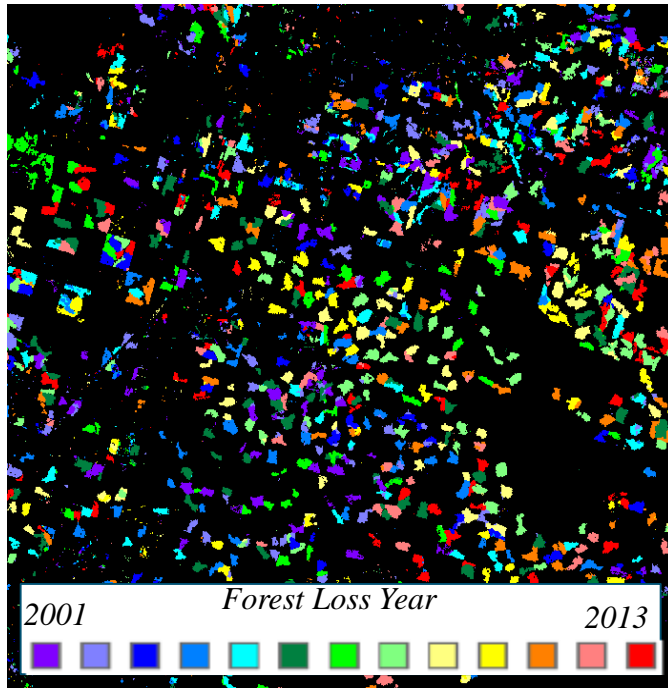
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Disturbance type characterization in the CONUS

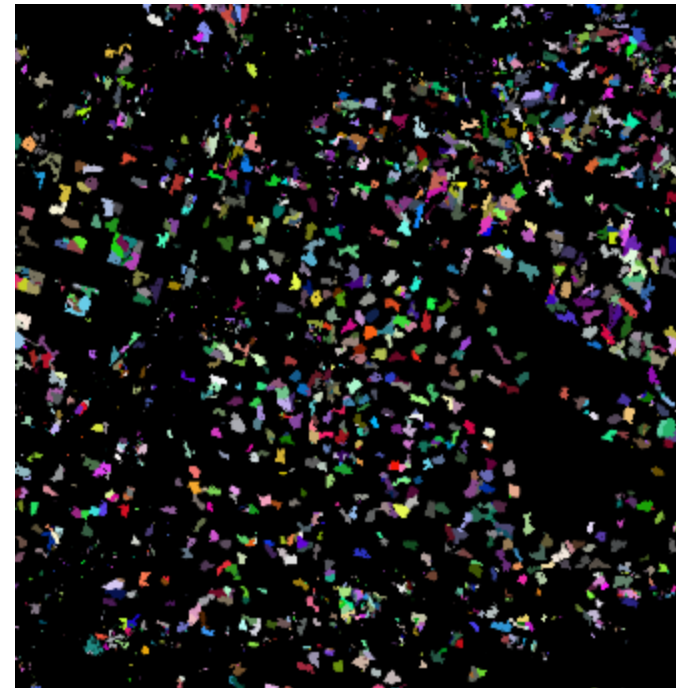


1 – Segmentation



Forest cover loss map

Forest cover loss *objects*:
8-neighbourhood connectivity
Same forest cover loss year



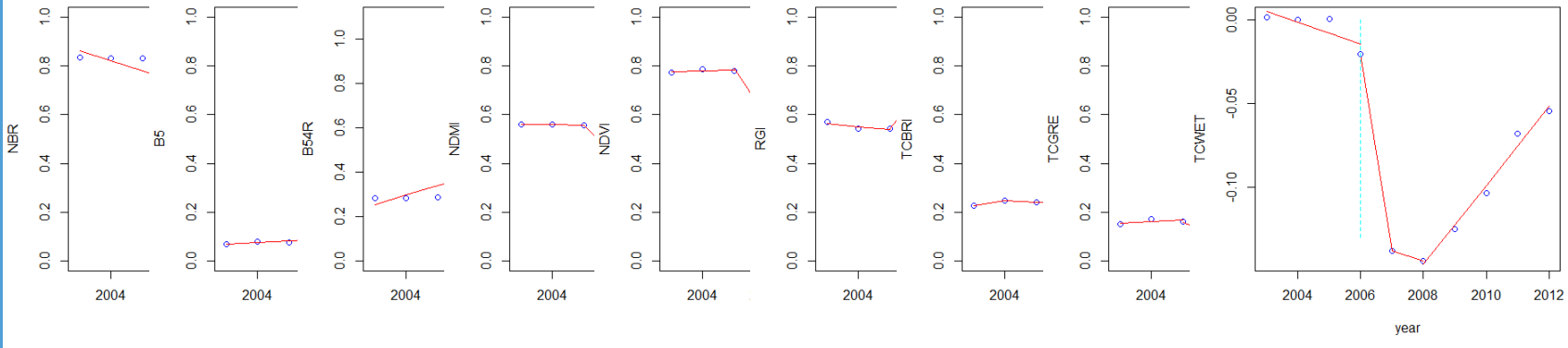
Temporal analysis

Object-oriented version of the LandTrendr Algorithm (Kennedy et al, 2010)

- Time series of spectral indices for each object, extracted from the WELD annual composites
 - RGI, NDVI, NDMI, B54R, NBR, ρ_{B5} , TC_{BRI} , TC_{GRE} , TC_{WET}
- Temporal segmentation of the trajectory
- Classification based on the trajectory characteristics

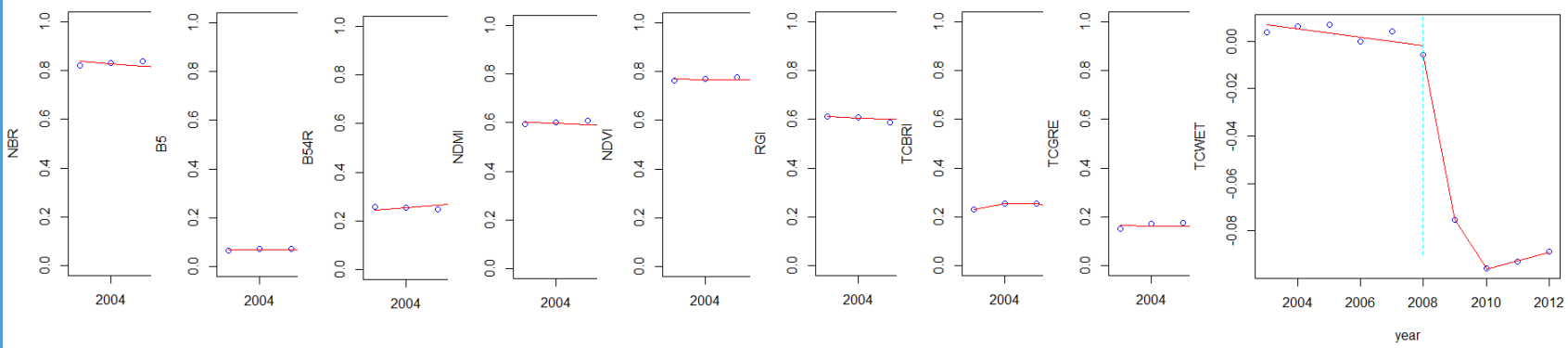
CLEARCUT

h03v04-56507



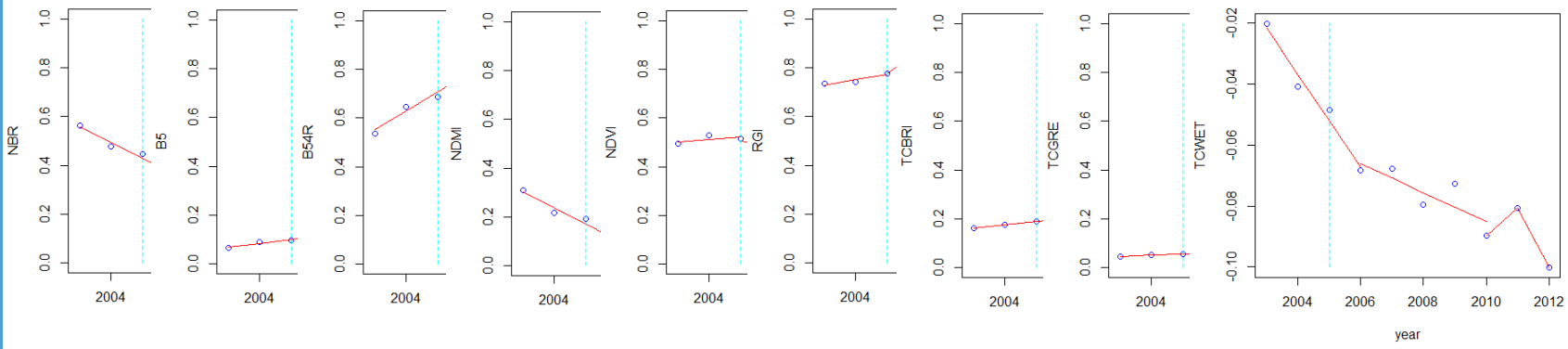
FIRE

h02v06-156745

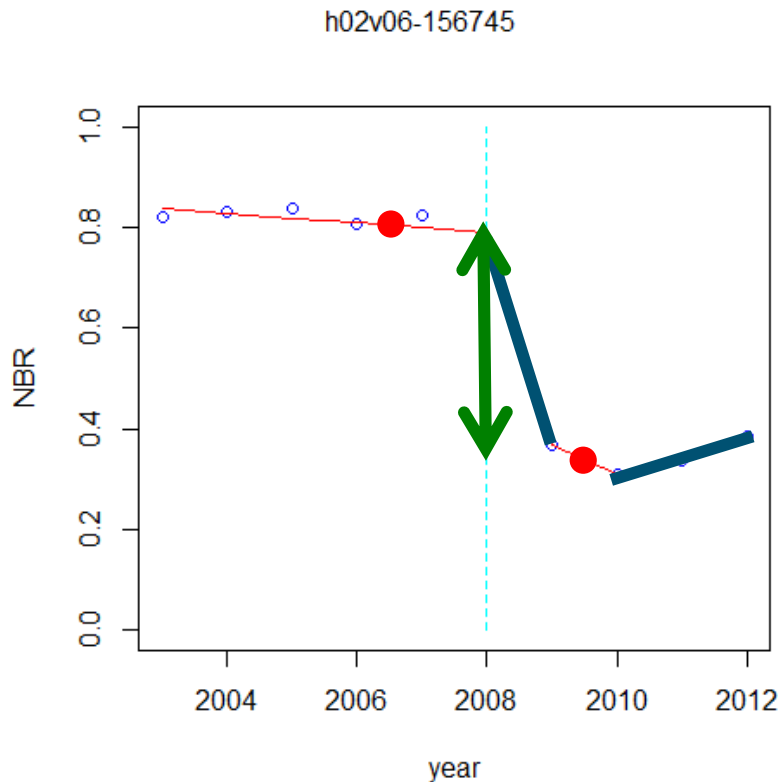


INSECT OUTBREAK

h11v09-58121



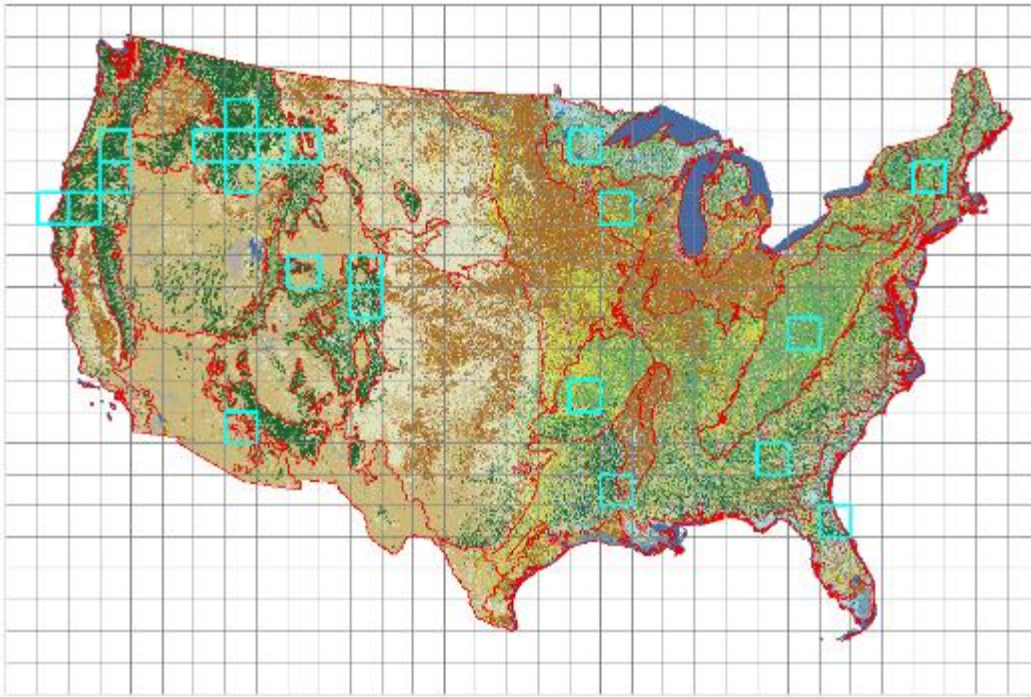
Temporal Trajectory Segmentation



Representative parameters:

- Minimum and maximum slope
- Average value in the 2 years before and 2 years after the disturbance
- Magnitude of the change between the two average values

Random forest classification: training data

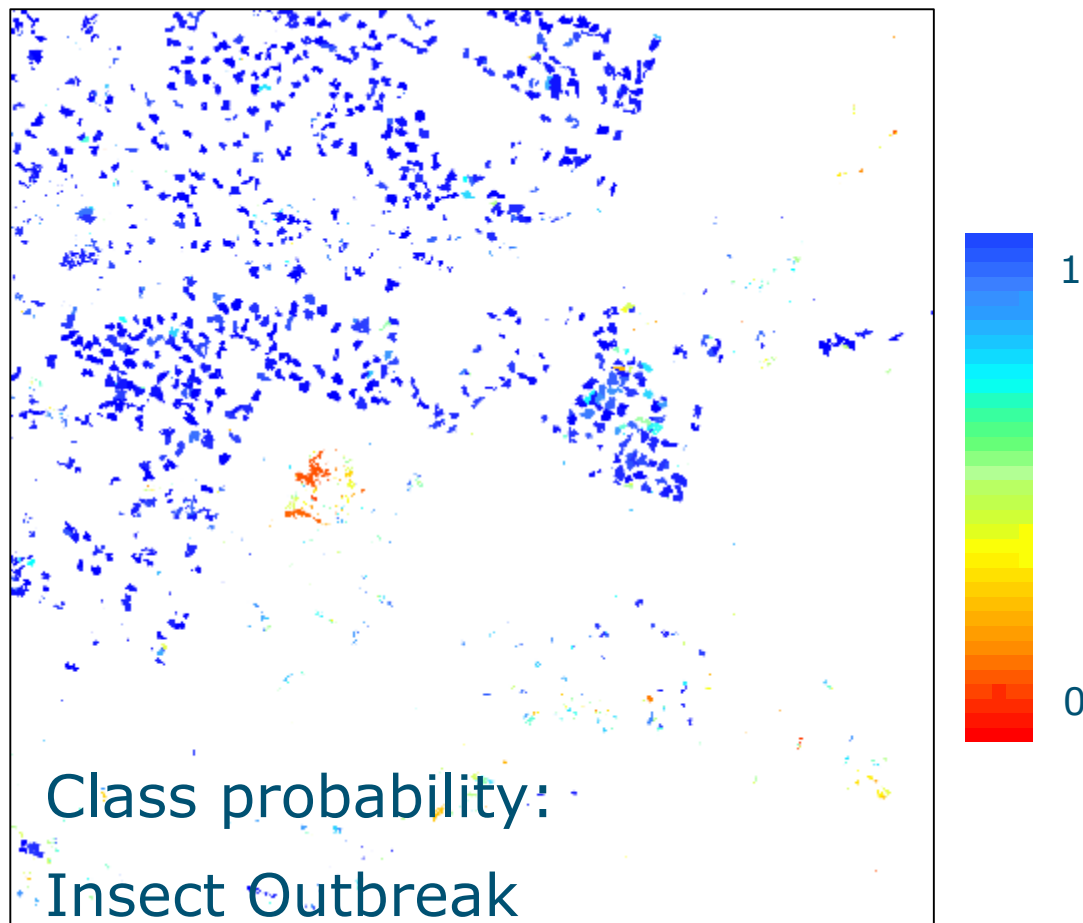


Training set of ~ 2000 forest cover loss objects of known disturbance types

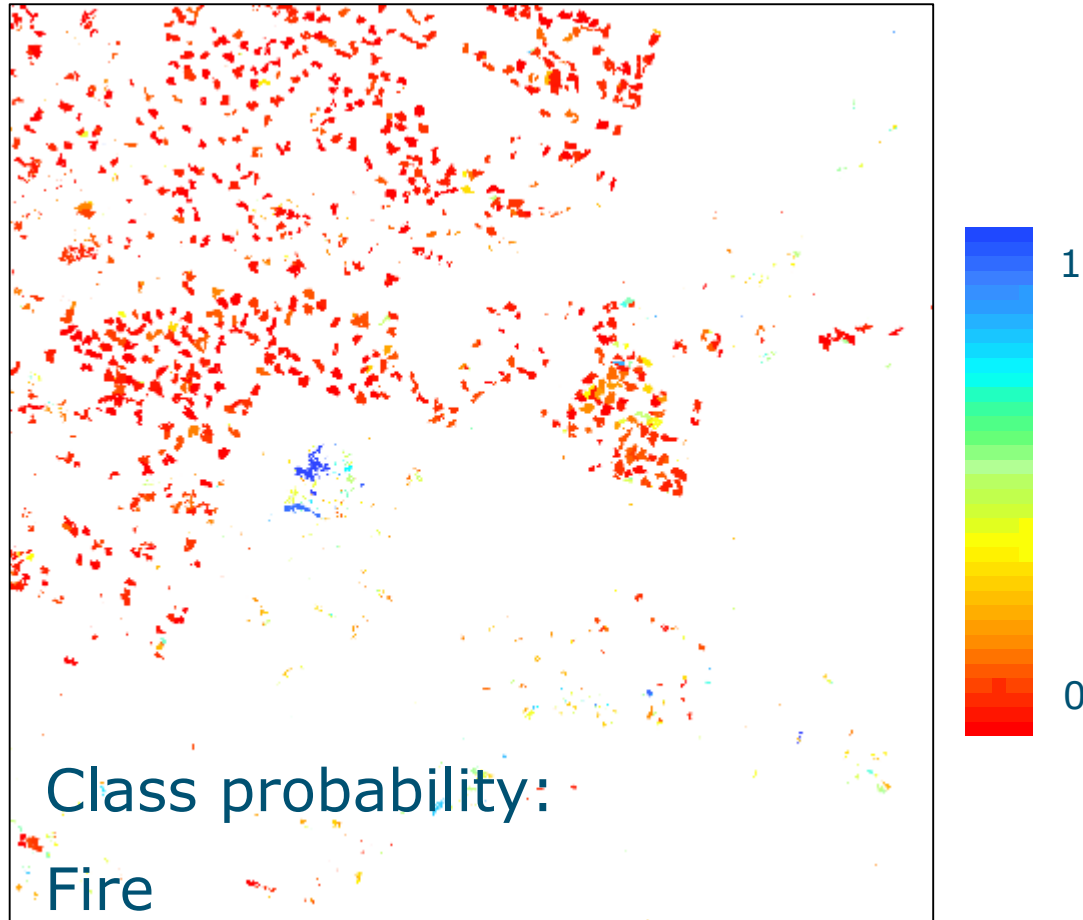
Visual interpretation of:

- WELD composites
- USDA NAIP aerial photos
- high resolution satellites imagery
- ancillary datasets (MTBS perimeters and USFS insect outbreak locations)

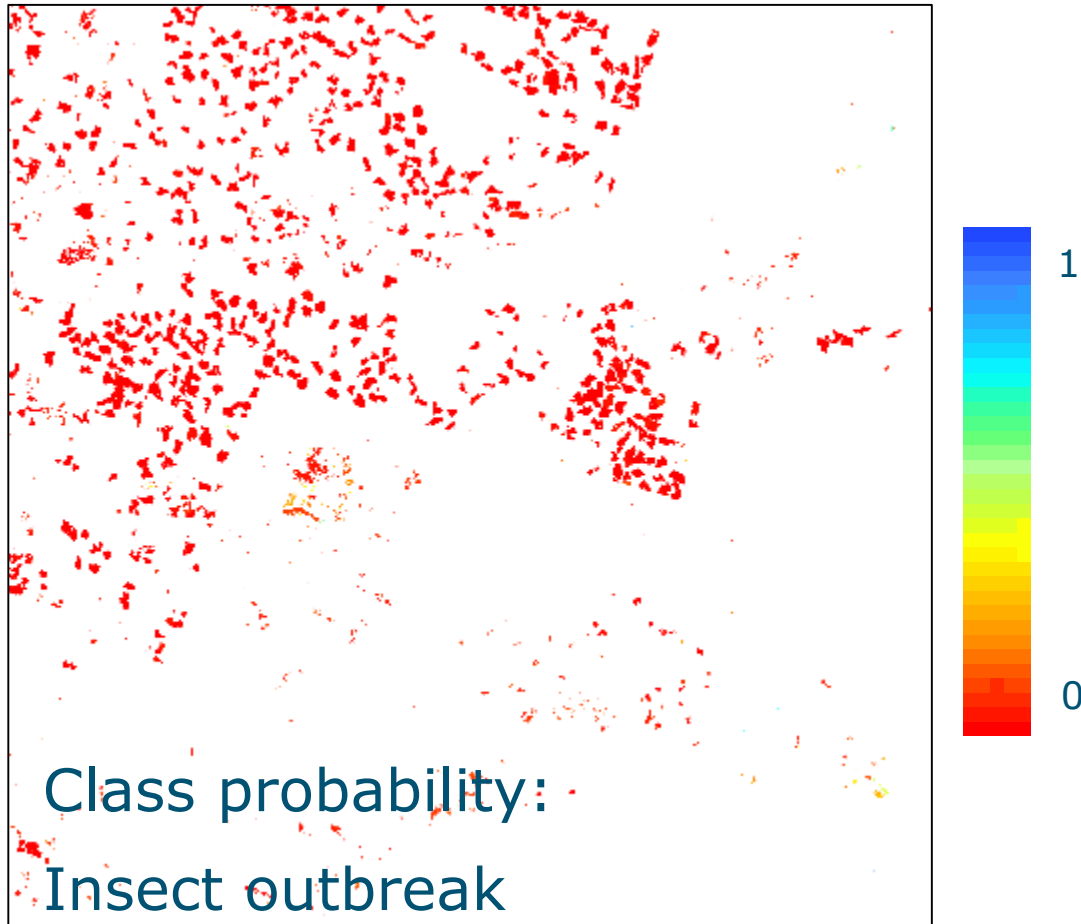
Random forest classification output



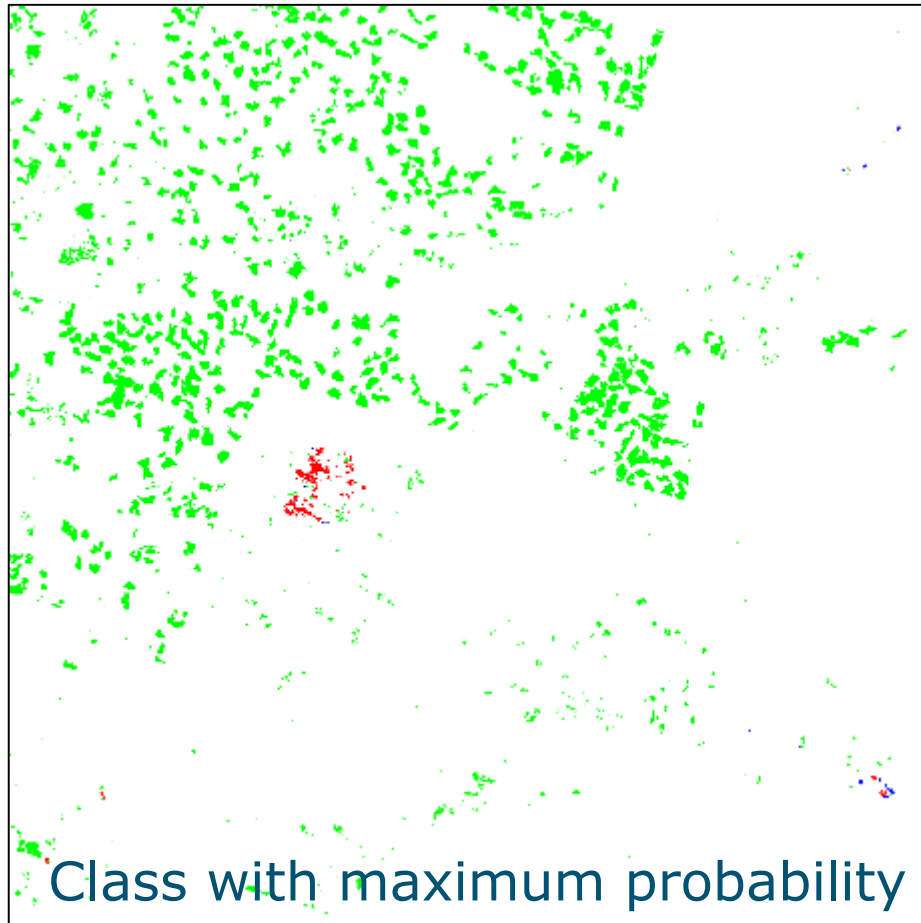
Random forest classification output



Random forest classification output

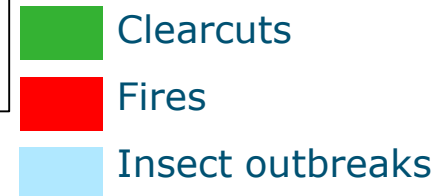
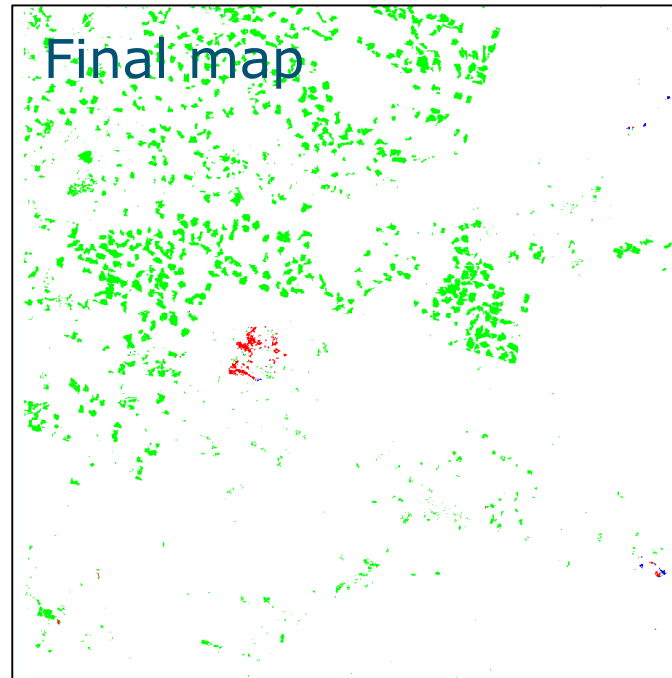
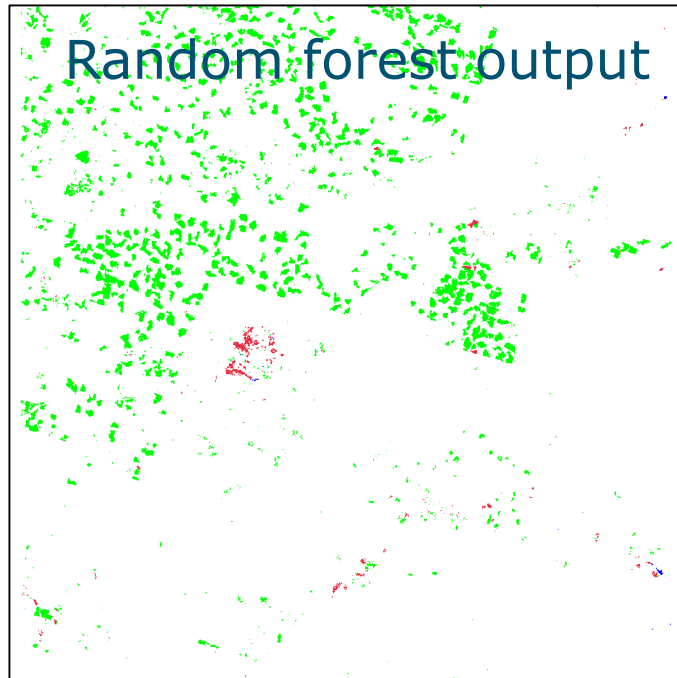


Random forest classification output

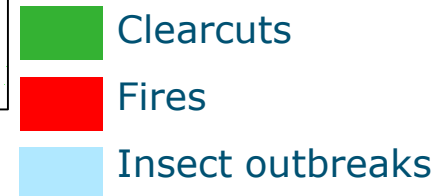
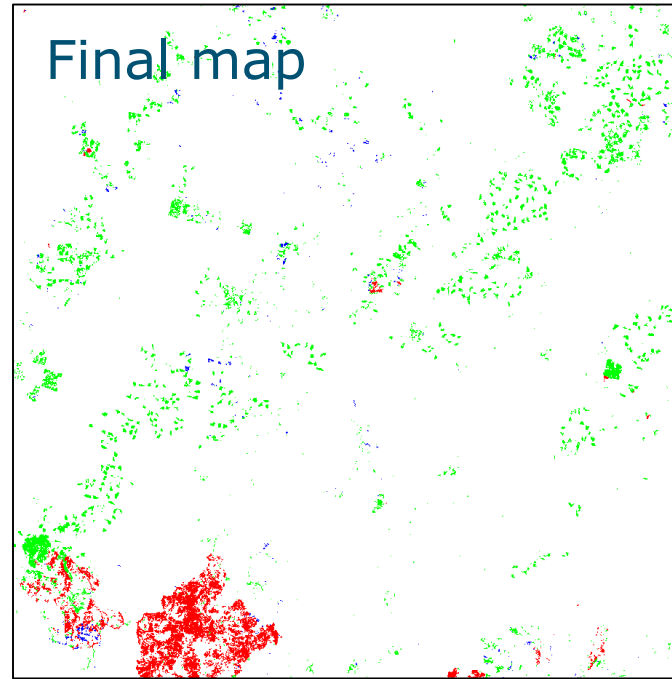
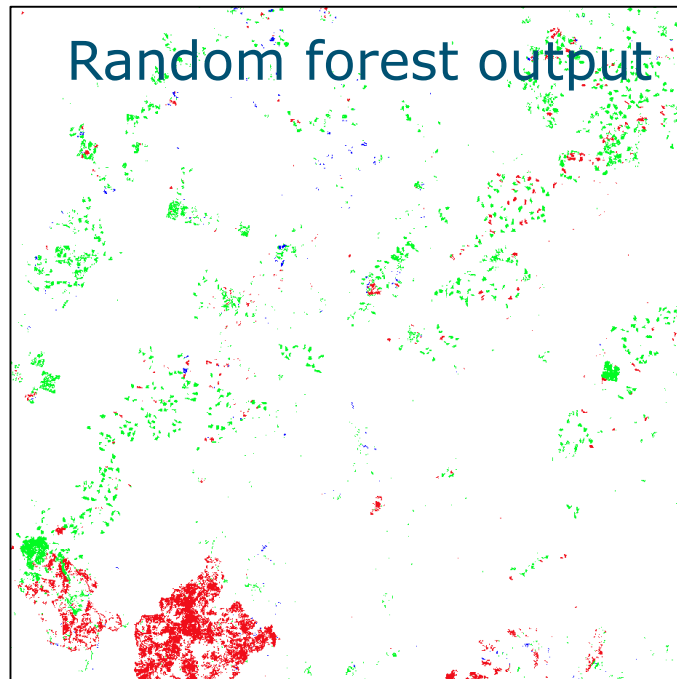


- Clearcuts
- Fires
- Insect outbreaks

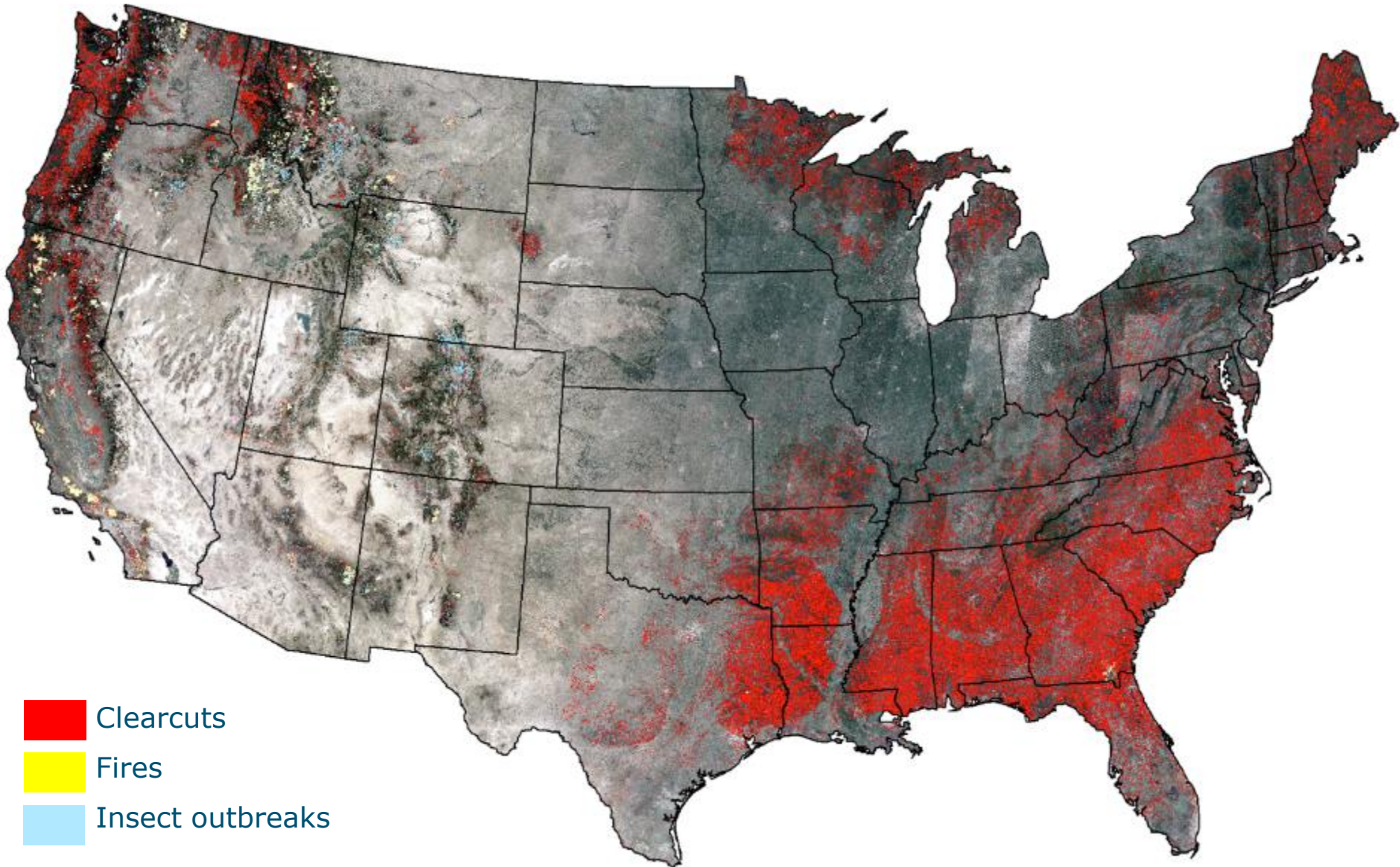
Post classification with MODIS active fires



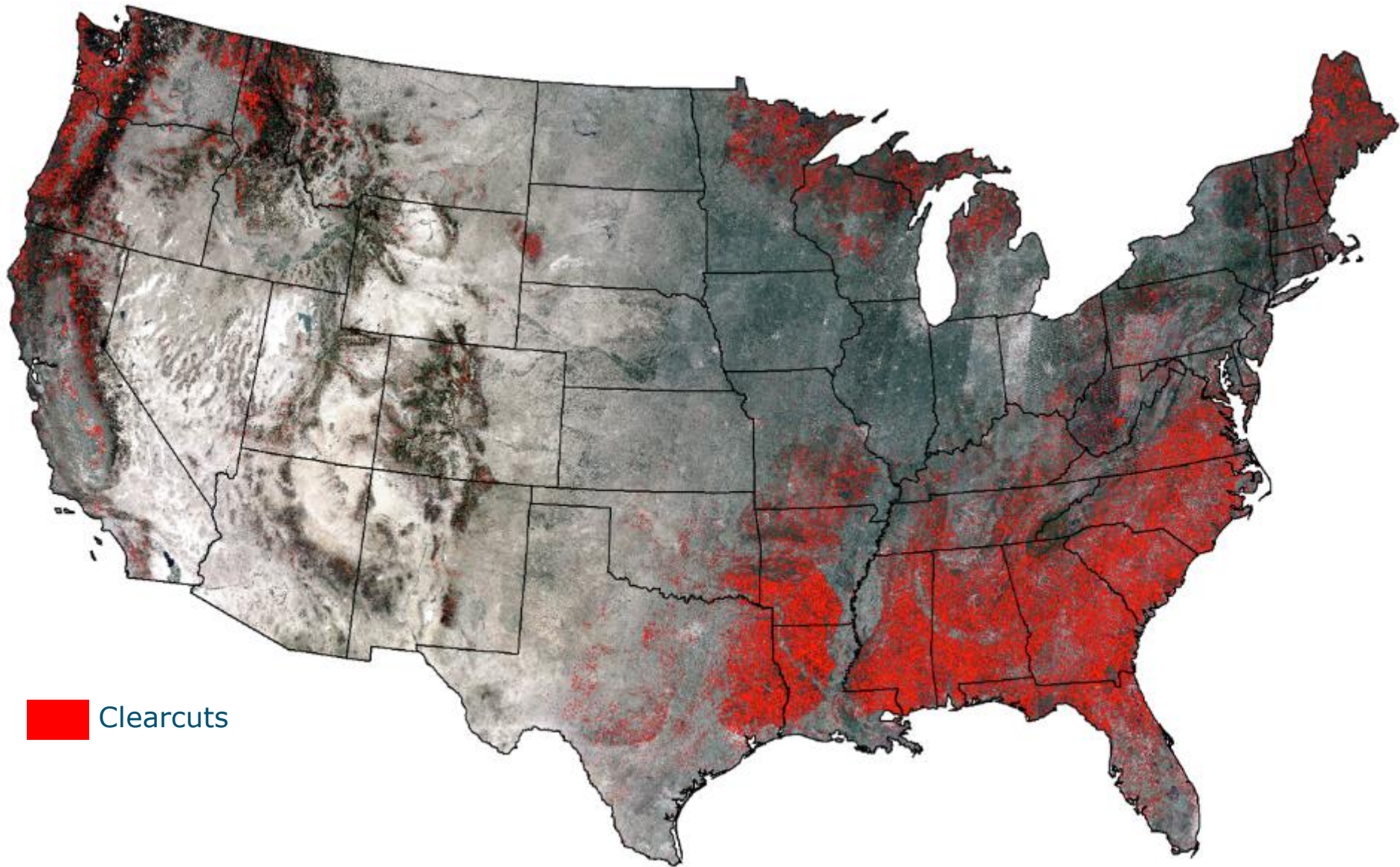
Post classification with MODIS active fires



2004-2011 forest disturbances

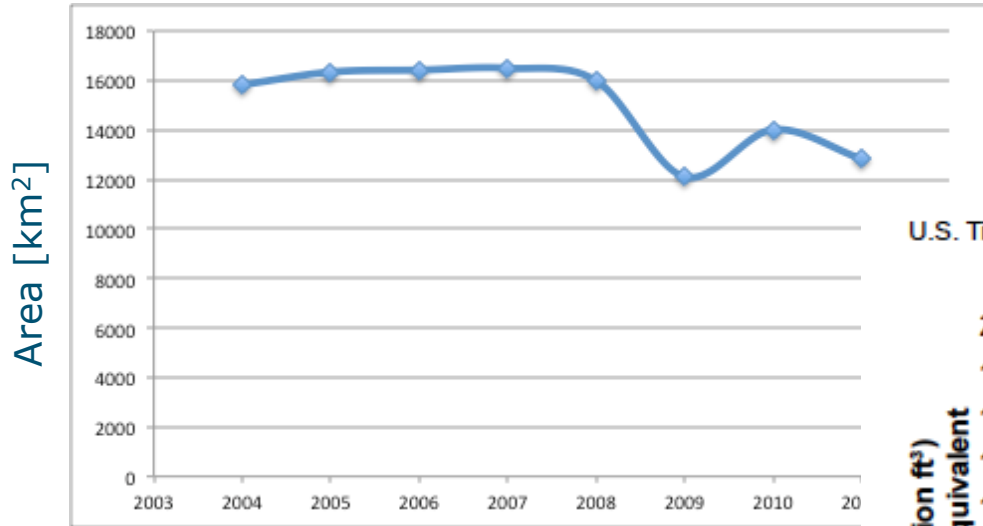


2004-2011 Clearcuts

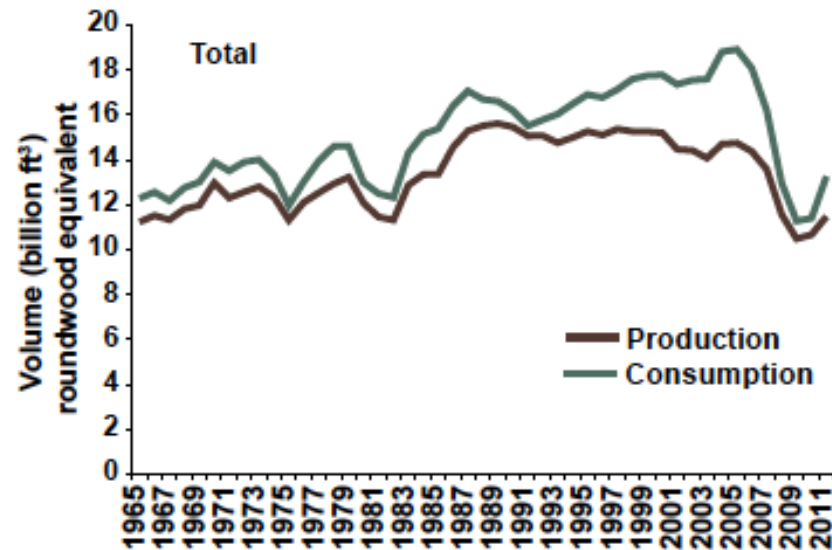


Clearcut trends

CONUS clearcuts

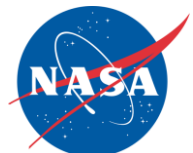


U.S. Timber Production, Trade, Consumption and Price Statistics 1965–2011

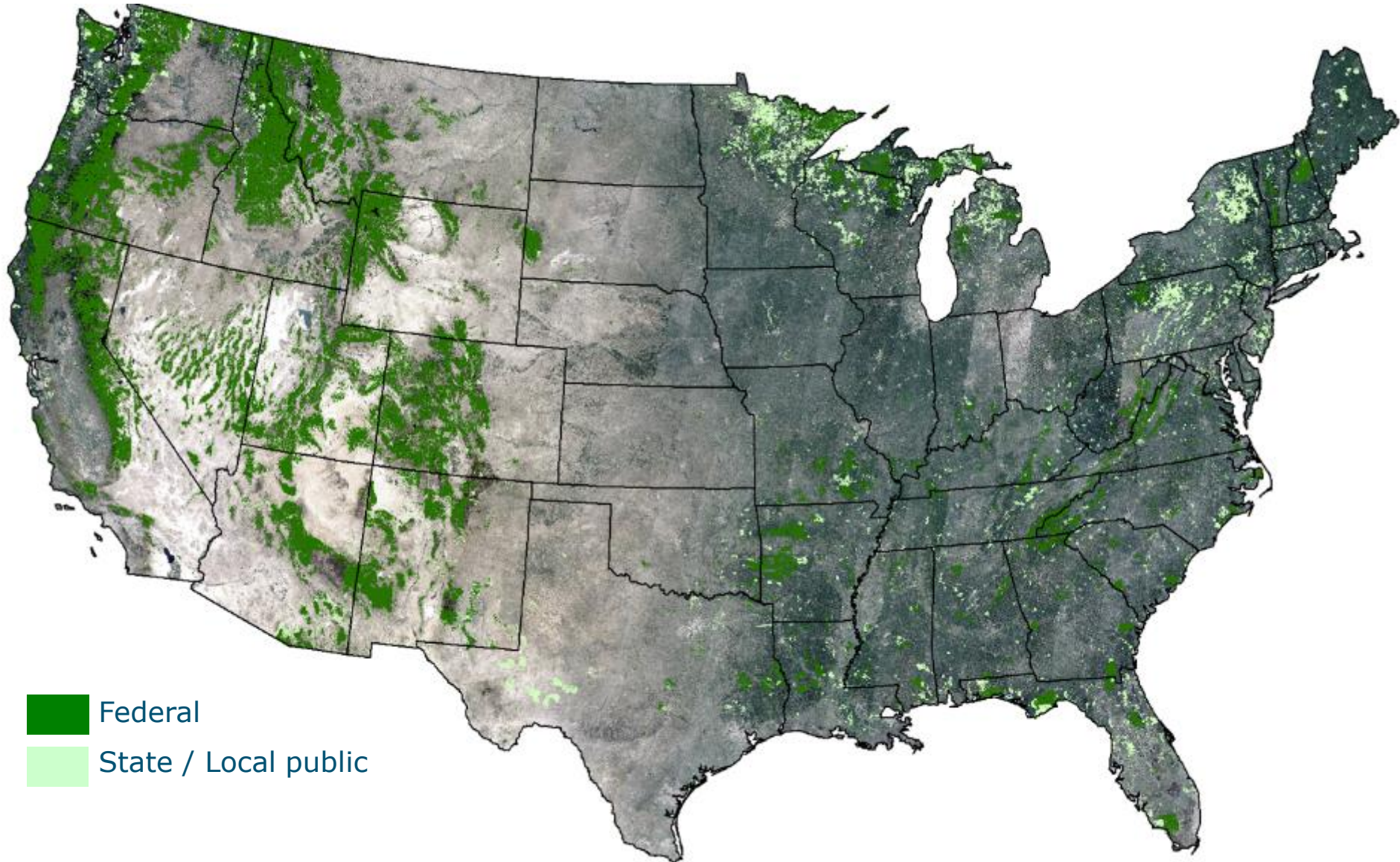


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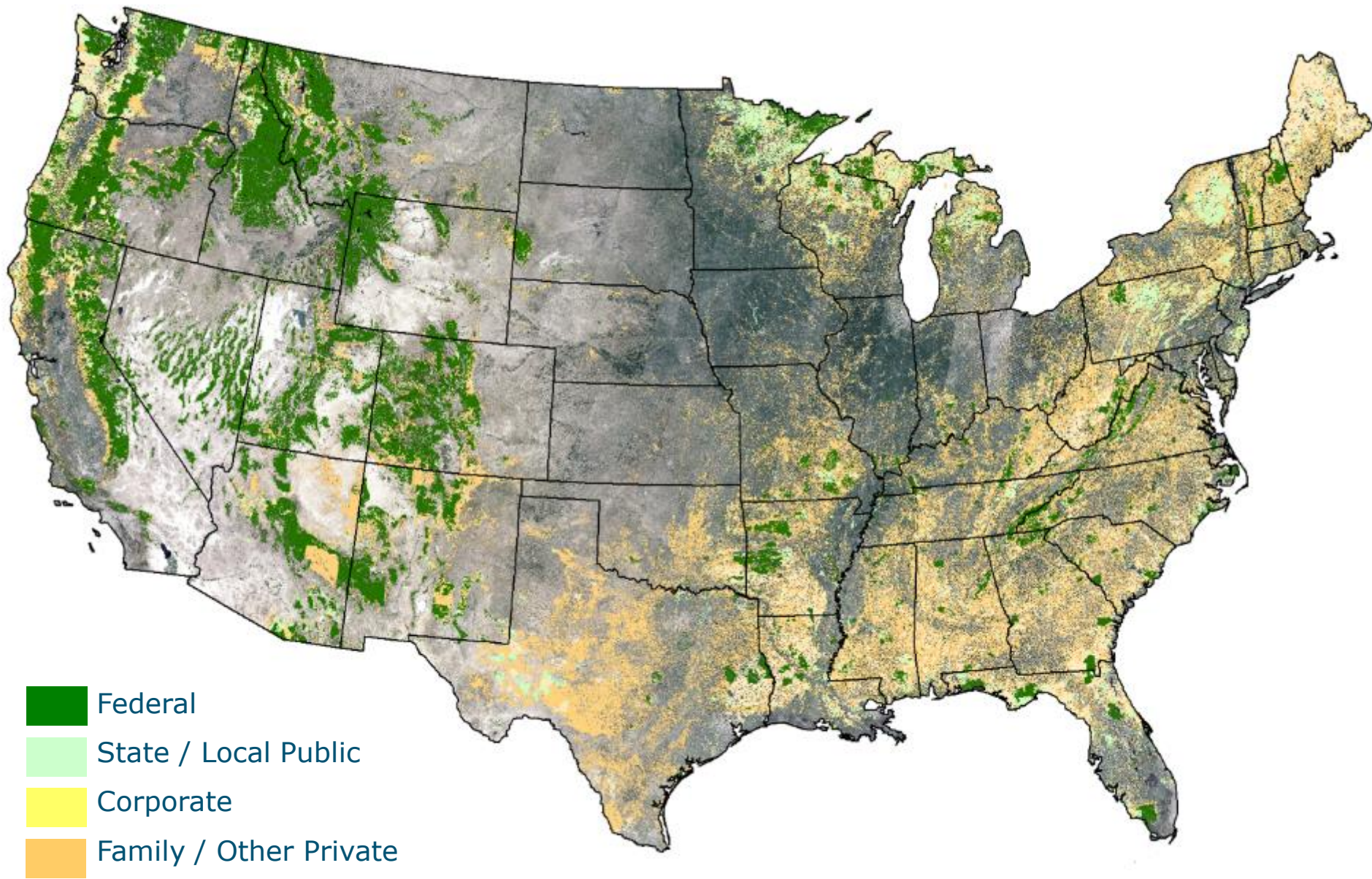
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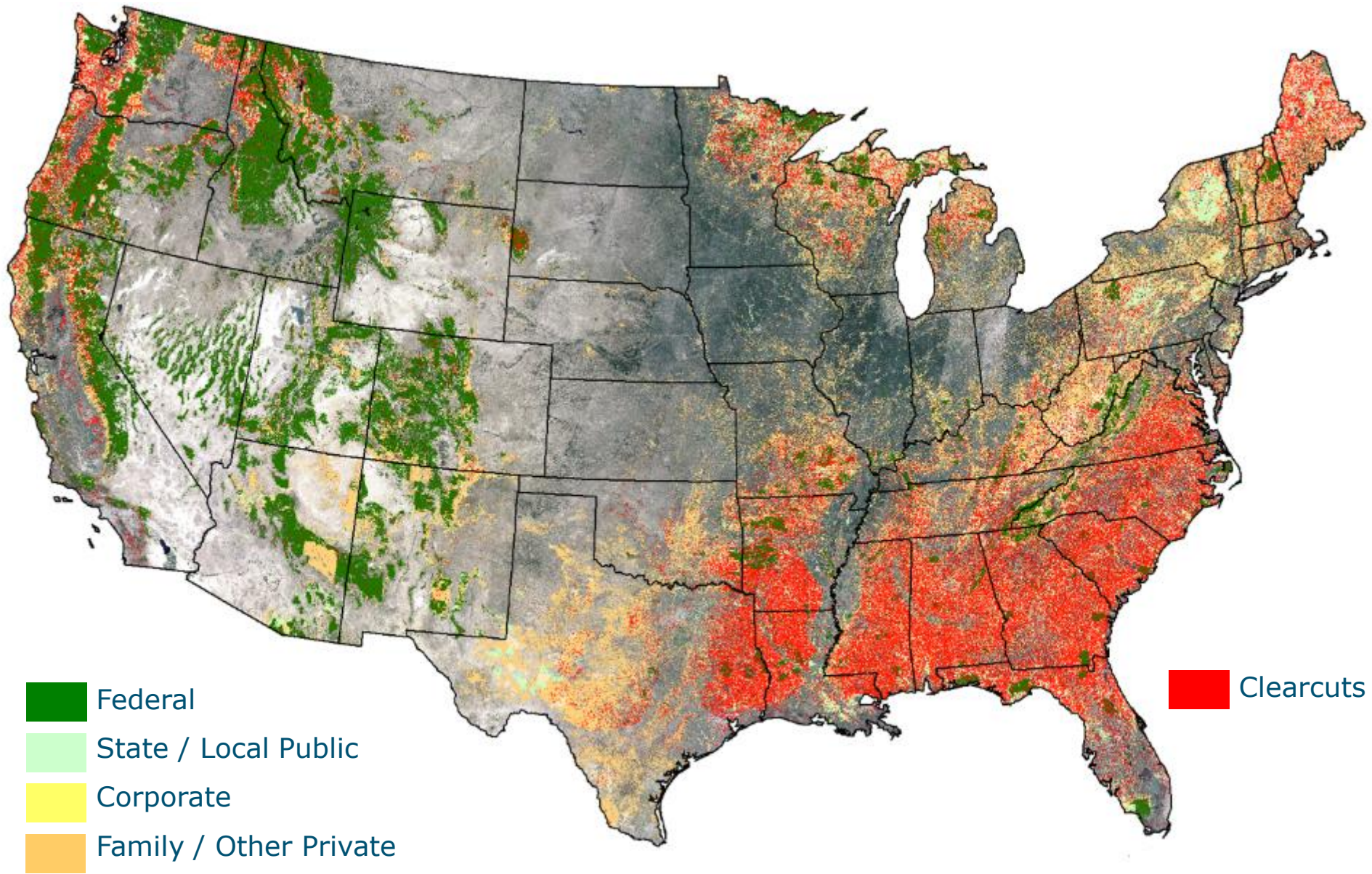
Forest Ownership: Public



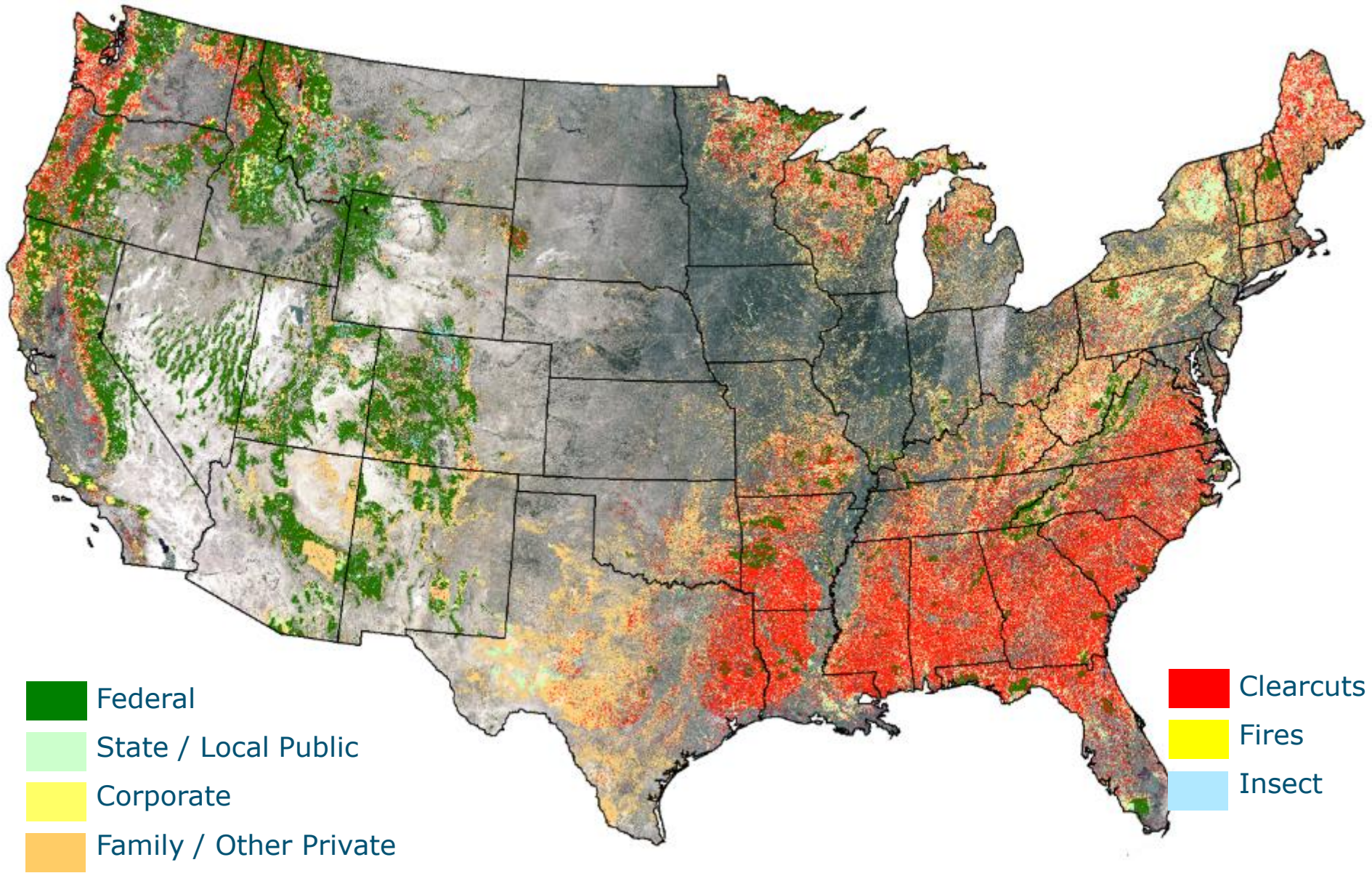
Forest Ownership: Public and Private



Disturbances and Land Ownership

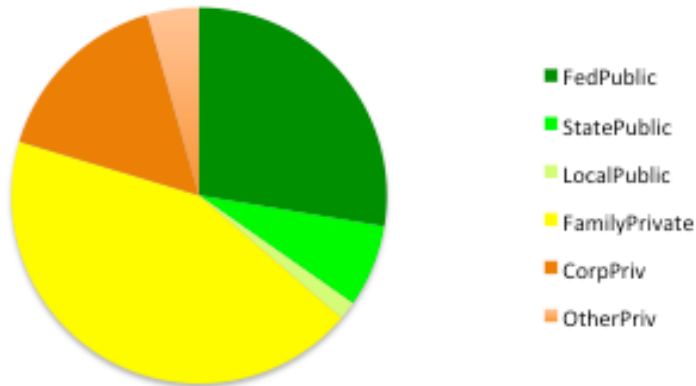


Disturbances and Land Ownership

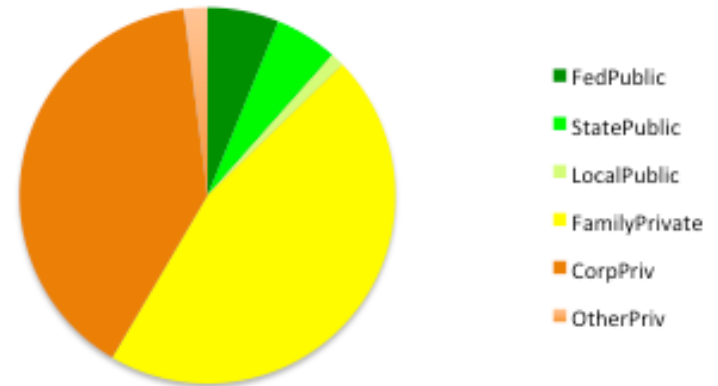


Disturbances and Land Ownership

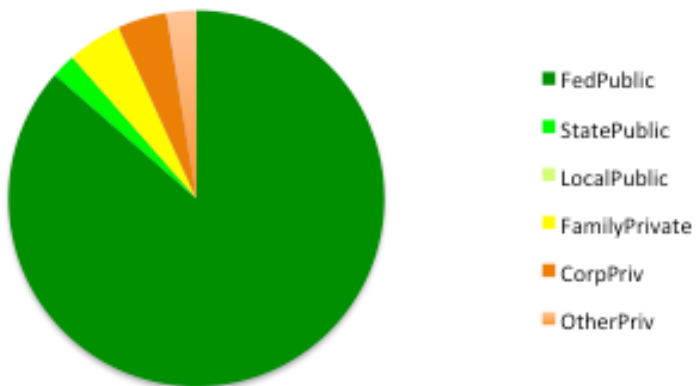
Forest Ownership



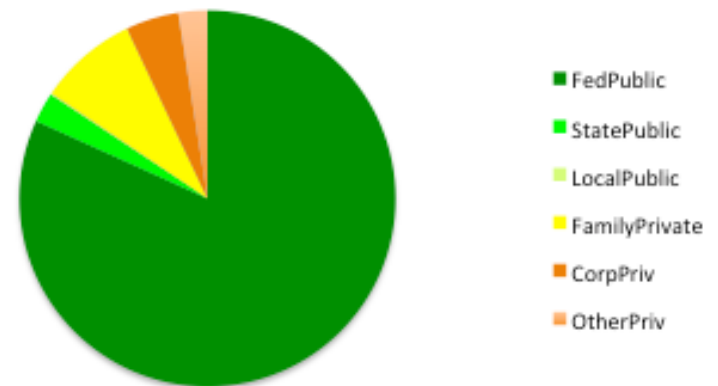
2004-2011 Clearcut Area



2004-2011 Fire Area



2004-2011 Insect Damage



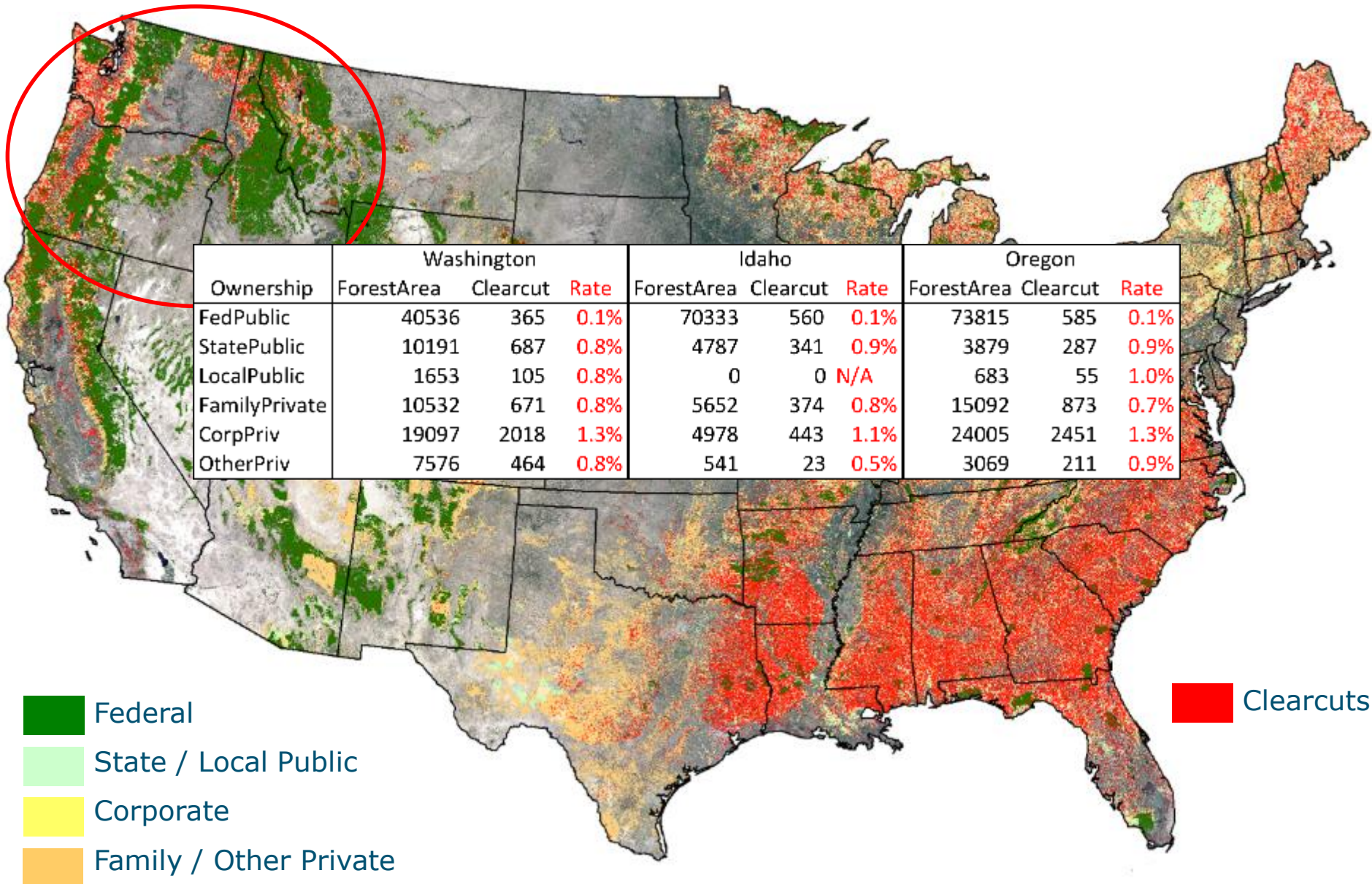
Ind

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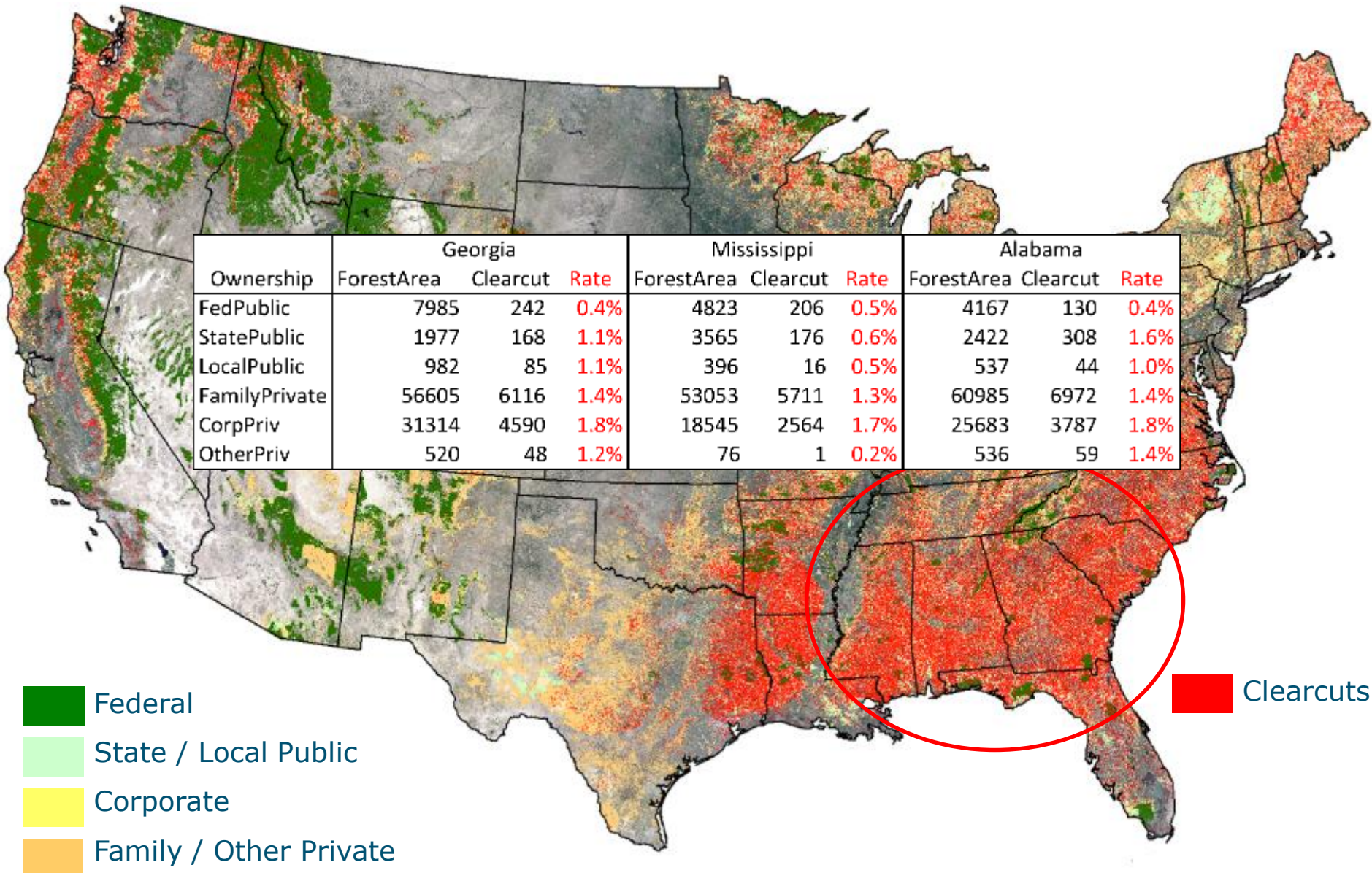
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Disturbances and Land Ownership



Disturbances and Land Ownership



What is the logging rate? Is it sustainable?

	Northwest	Northeast	Midwest	Southeast
Forest type	Dry and moist conifer	Spruce	Northern & central hardwoods	Southern pine
Rotation - Sawlogs	50-60 yr	60-80 yr	80-100 yr	25 yr
Rotation -Pulp	20 yr	20 yr	-	12-15 yr
General silvicultural practices	Thin at age 12-14, possible thin 10 yrs before harvest	Thin at age 12-14, possible thin 10 - 15 yrs before harvest	Multiple thinnings, first at age 20-25	Row crop plantation; intensive fertilization and thinning
Final harvest regeneration system	Clearcut	Partial harvest	Clearcut	Clearcut
Maximum clearcut size – State law	California: 8.1 ha Oregon: 48.6 ha Washington: 97.1 ha Idaho: 40.5 ha on state lands; otherwise, no limit	Maine: 97.1 ha with restrictions; New Hampshire, Vermont, New York: No limit	No limit	No limit

What's next

- Refinement of the methodology
- Validation and uncertainty assessment (spatial and temporal)
- Is forest harvest in CONUS sustainable?
 - Clearcut rate by region and forest type
 - Comparison with rotation times

Current project activities

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Mapping the extent of the industrial forest

- Well defined for plantations, where it can be solved as a classic RS problem (tree specie mapping)
- Weakly defined for semi-natural plantations, where the vegetation composition is the same as natural vegetation. Remote sensing alone is not sufficient:
 - Ownership and protection status
 - Logging history shapes forest characteristics
 - Shape of homogeneous plots
 - Stand age

Tropical Plantations

- Brazil: eucalyptus



Tropical Plantations

- Malaysia: Oil Palm and Rubber



Industrial Forest in CONUS: semi-natural forest

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Characteristics of industrial clearcuts

- Logging practices are dictated by forest type, forest productivity, economic considerations, constraints due to regulations

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Distinctive Patterns: California



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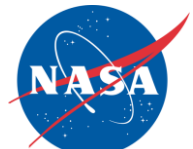


Distinctive Patterns: Maine



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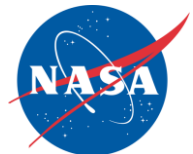


Distinctive Patterns: Oregon



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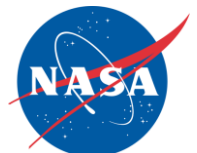
From Landsat...



Clearwater NF
(Idaho)

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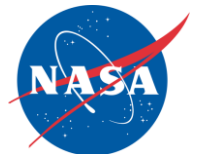
From Landsat...



Clearwater NF
(Idaho)

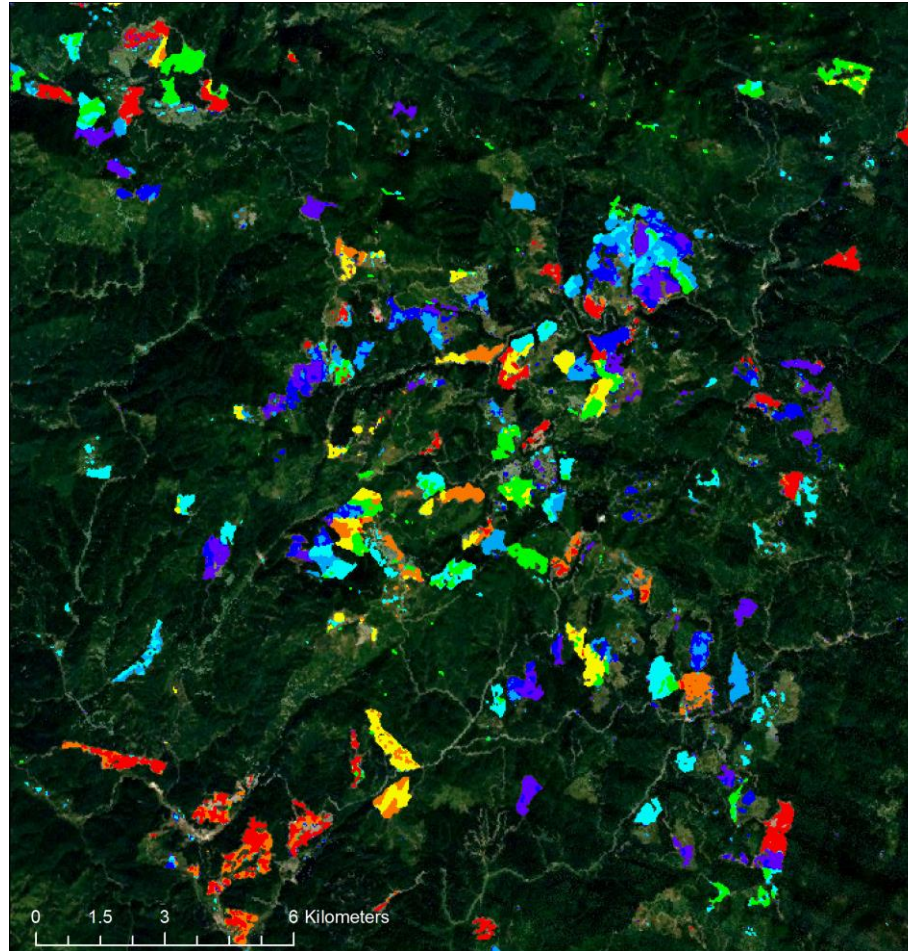
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From Landsat...

Clearwater NF
(Idaho)



Year



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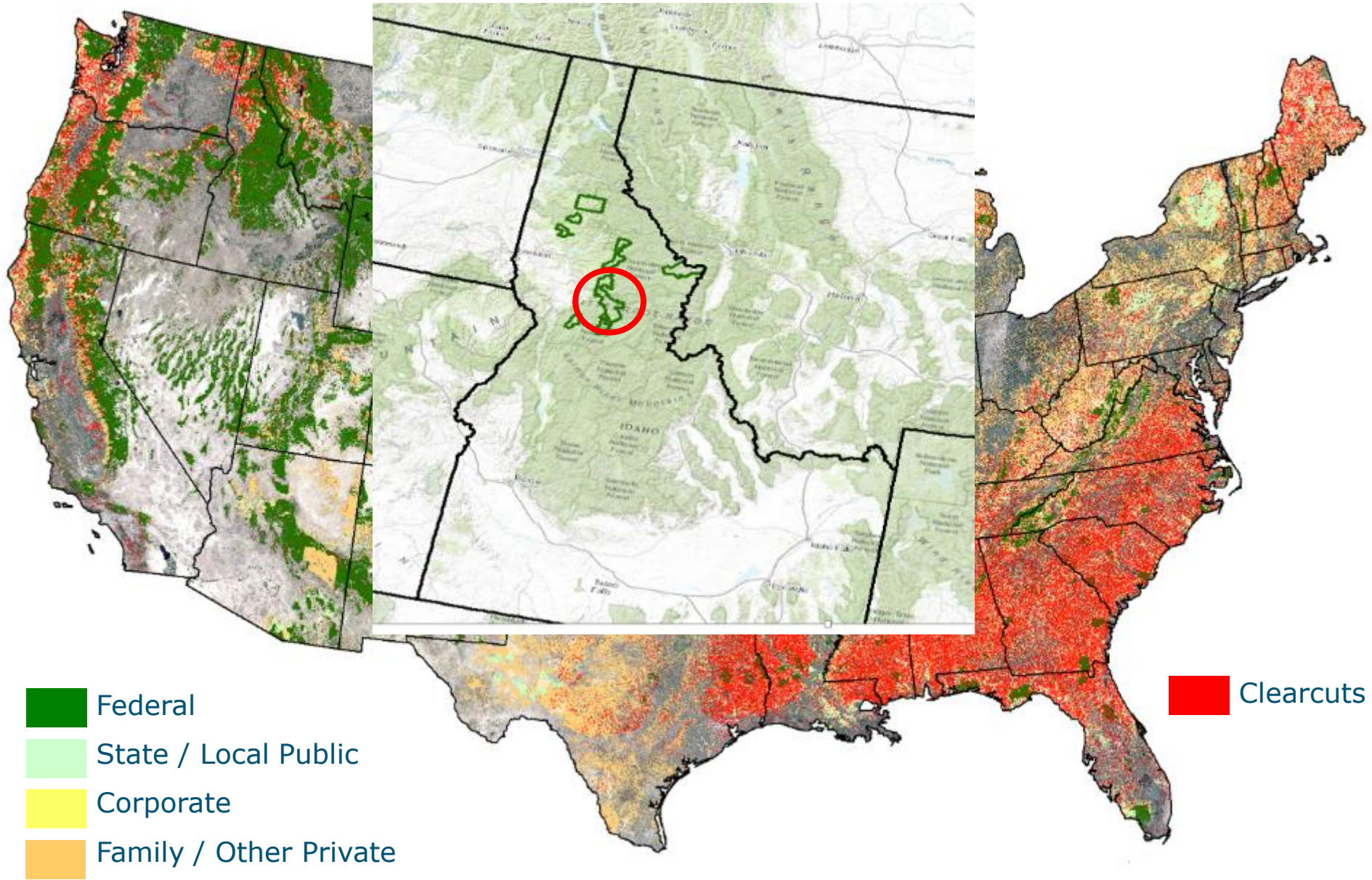
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Deforestation or forest management? Object-oriented classification

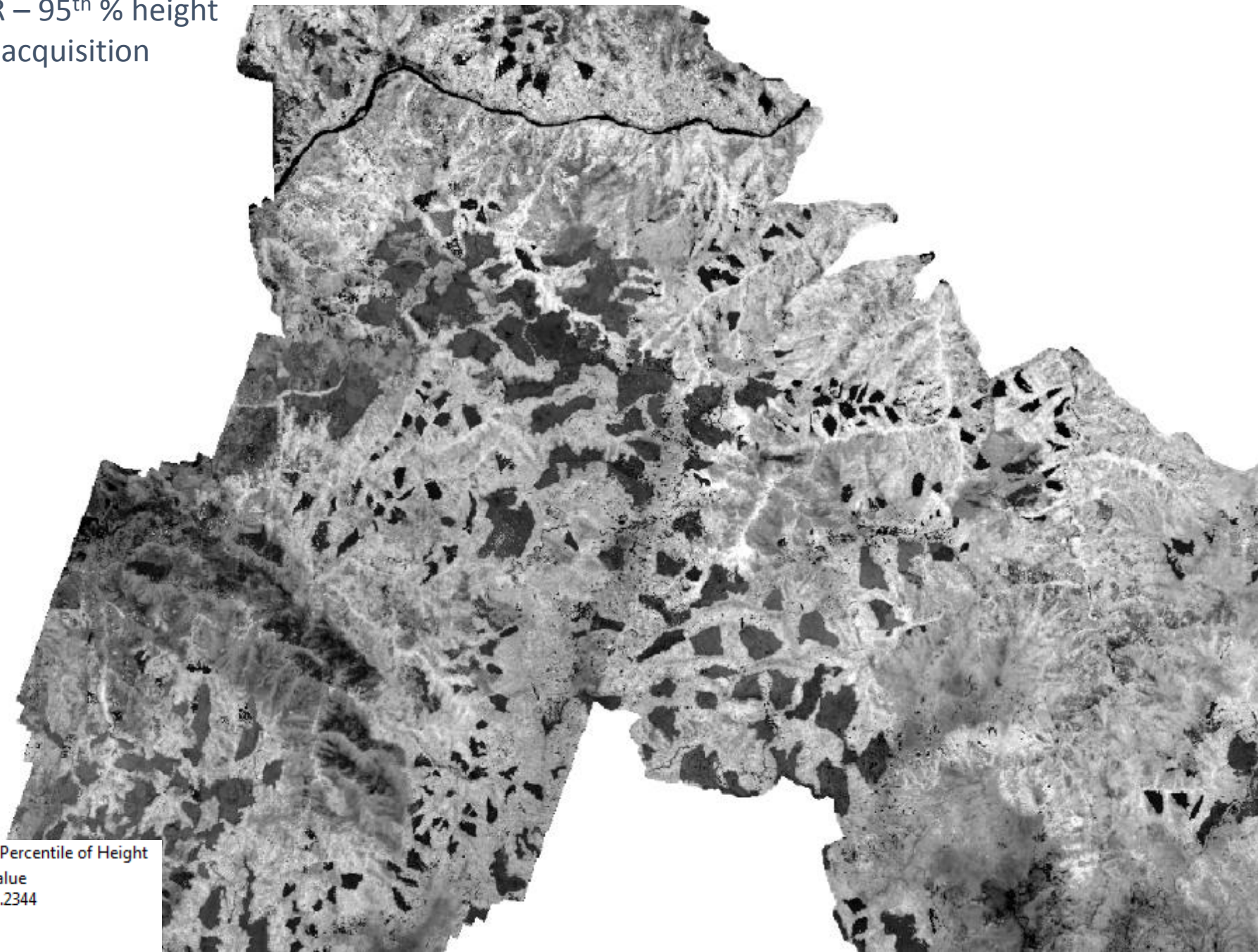
- Use of ancillary information about forestry practices
- Classification based on
 - Size
 - Shape (compactness, linear or curvilinear edges)
 - Contextual information
 - Presence or absence of logging in previous years
- LIDAR – Landsat data fusion

Detecting past clearcuts: LIDAR-L8 fusion



LIDAR – 95th % height
2012 acquisition

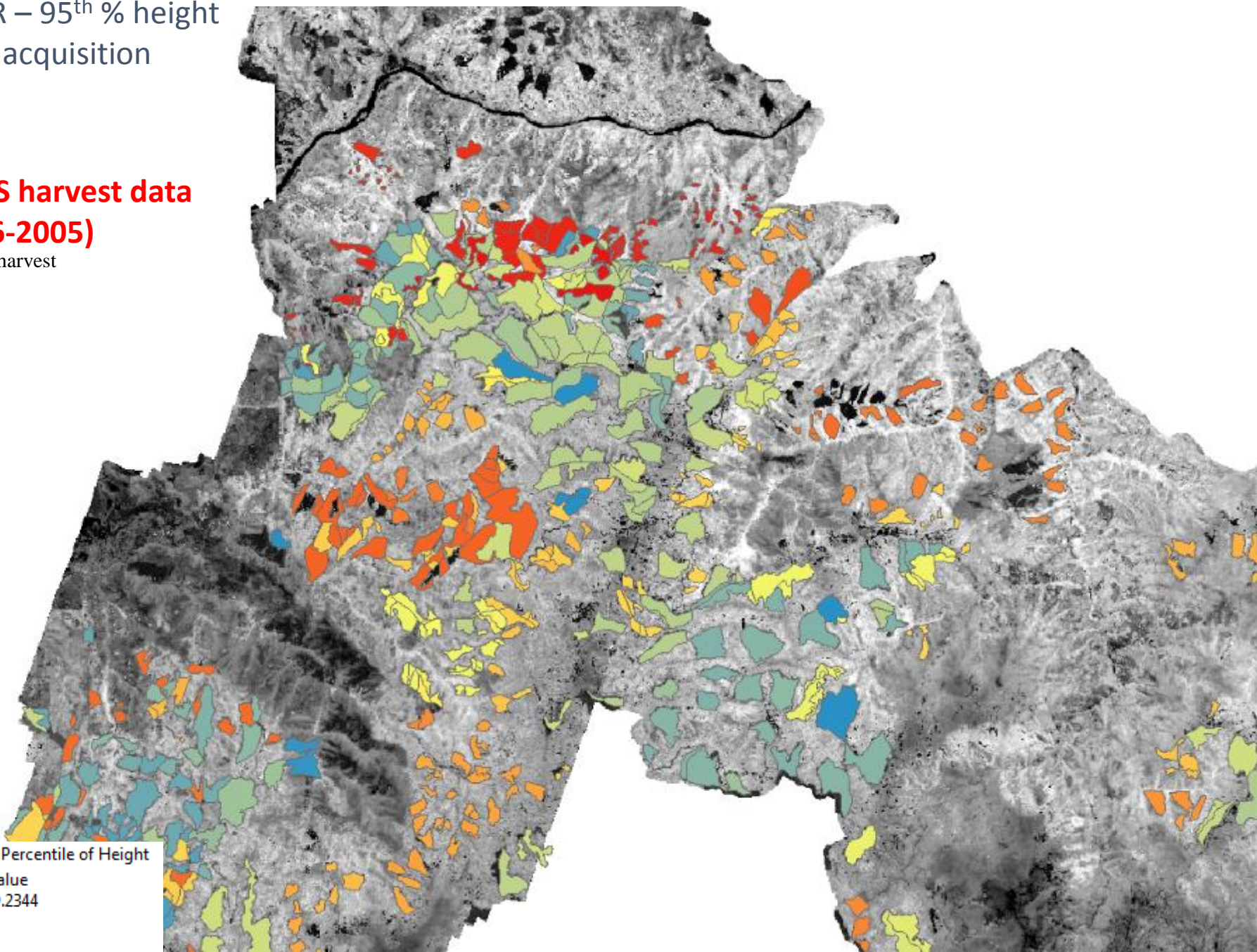
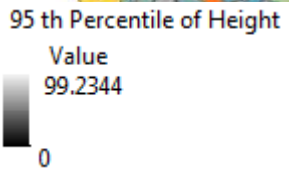
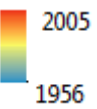
95 th Percentile of Height
Value
99.2344
0



LIDAR – 95th % height
2012 acquisition

**FACTS harvest data
(1956-2005)**

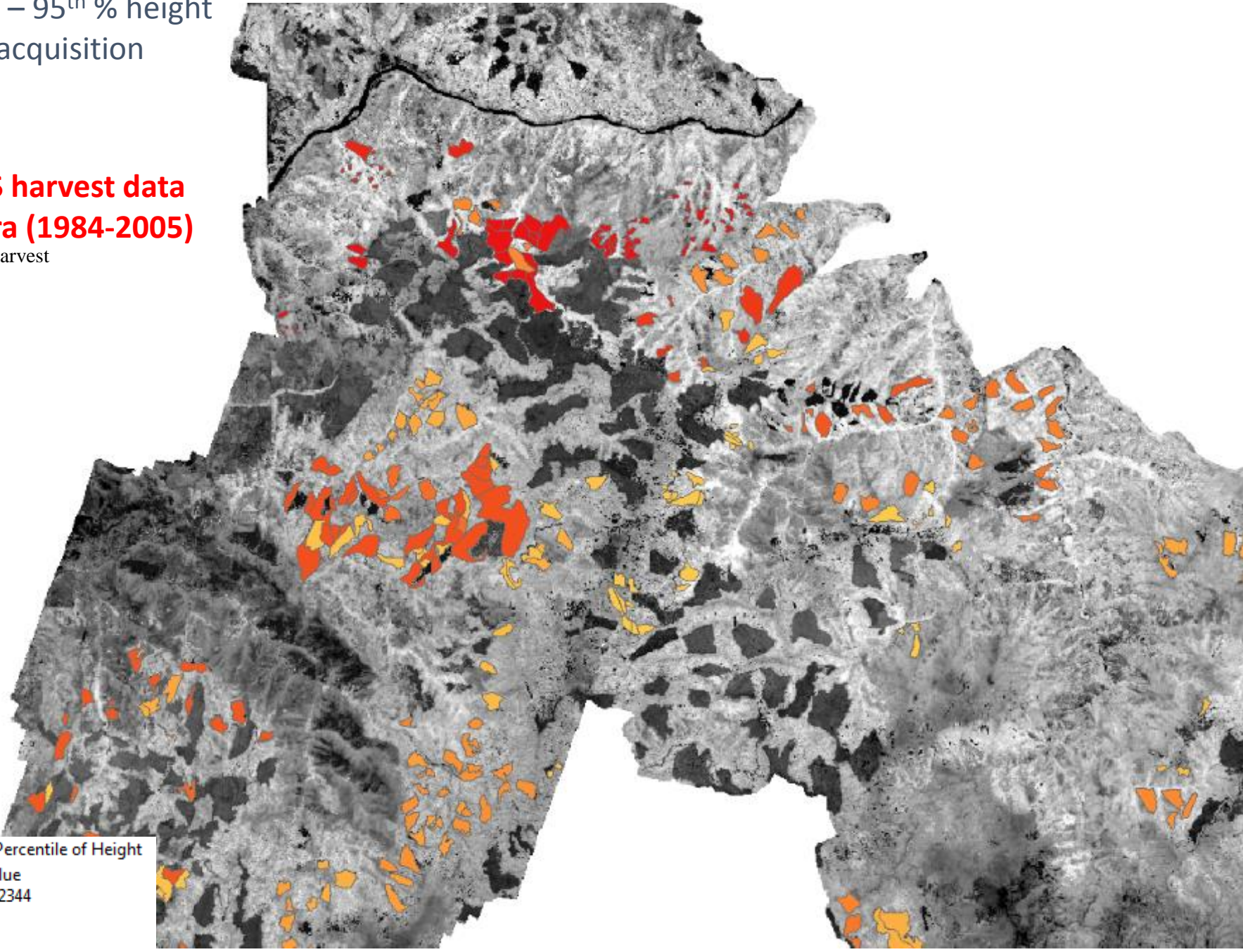
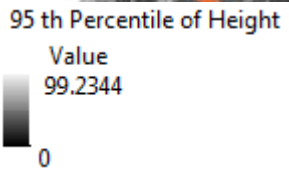
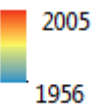
Year of harvest



LIDAR – 95th % height
2012 acquisition

FACTS harvest data
TM era (1984-2005)

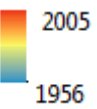
Year of harvest



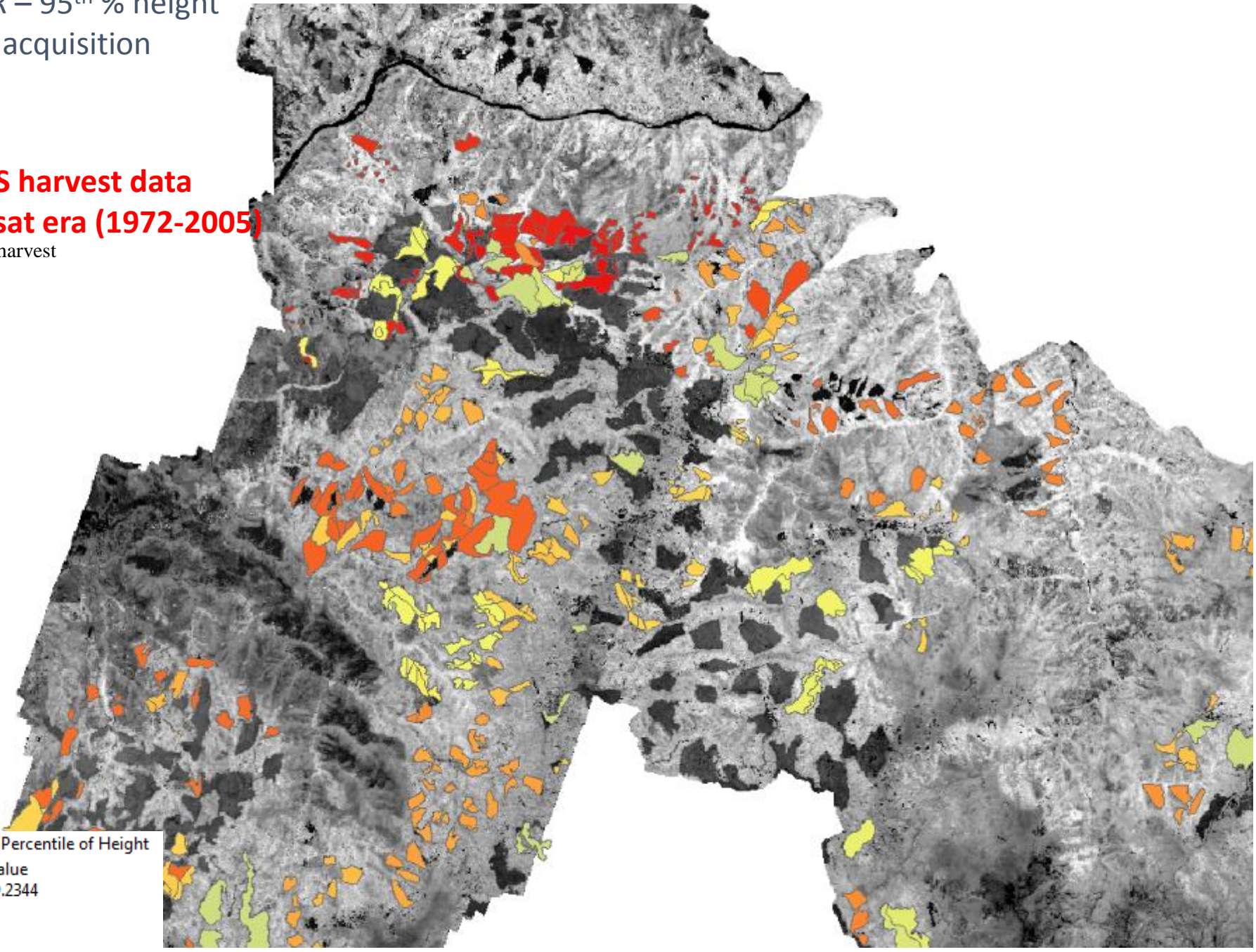
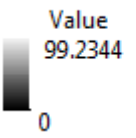
LIDAR – 95th % height
2012 acquisition

FACTS harvest data
Landsat era (1972-2005)

Year of harvest



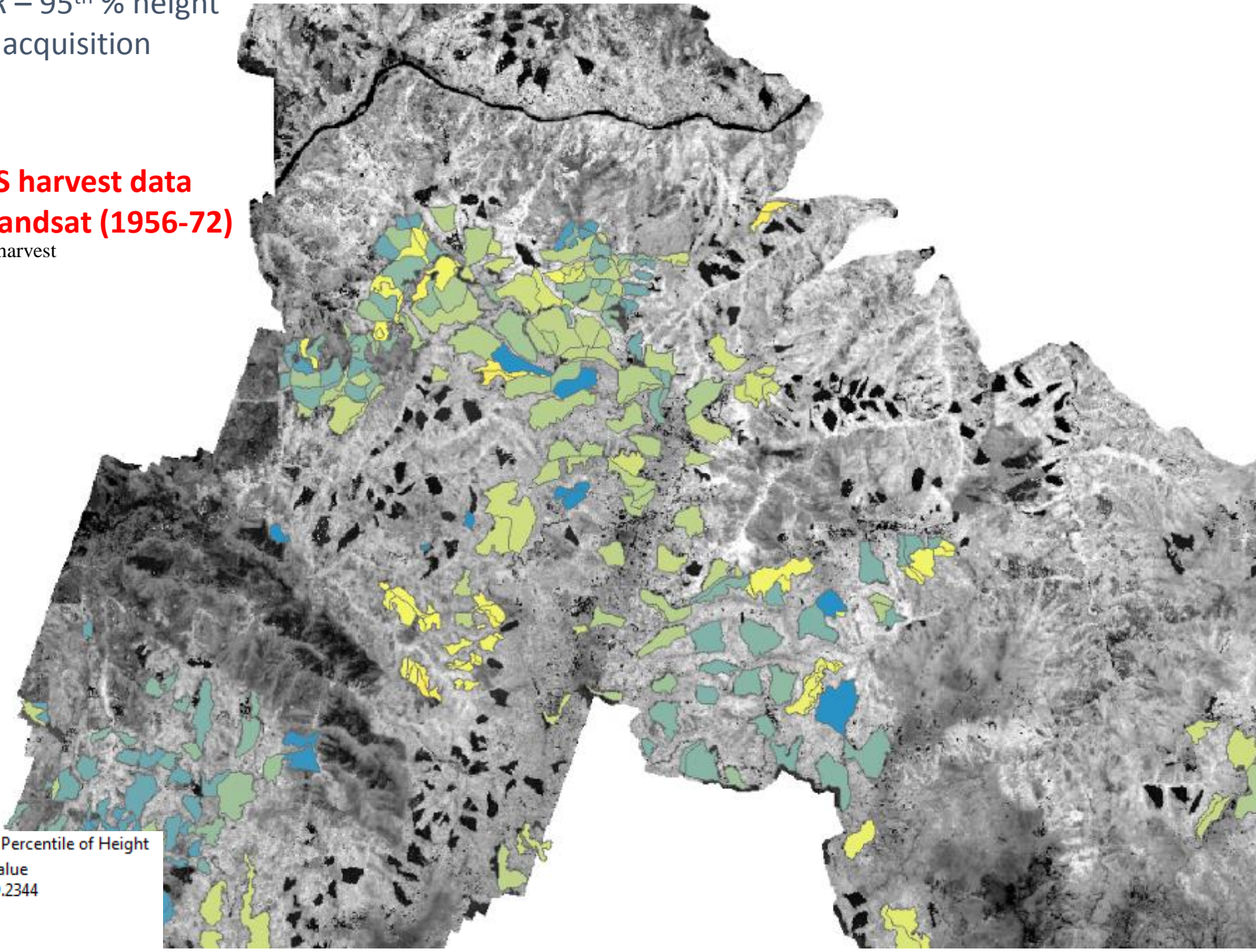
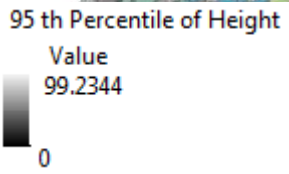
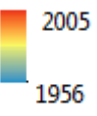
95th Percentile of Height



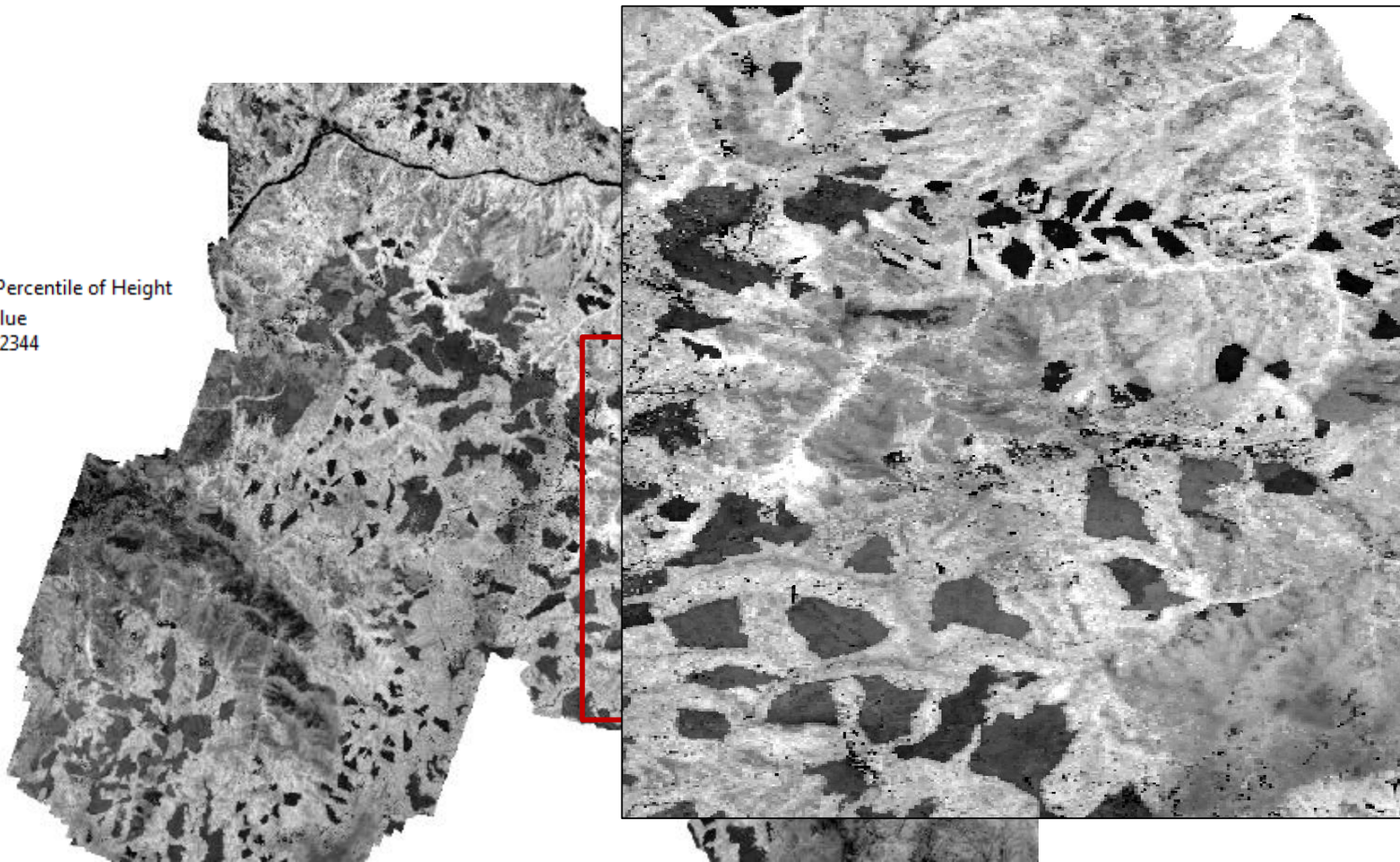
LIDAR – 95th % height
2012 acquisition

FACTS harvest data
Pre-Landsat (1956-72)

Year of harvest



95 th Percentile of Height
Value
99.2344
0



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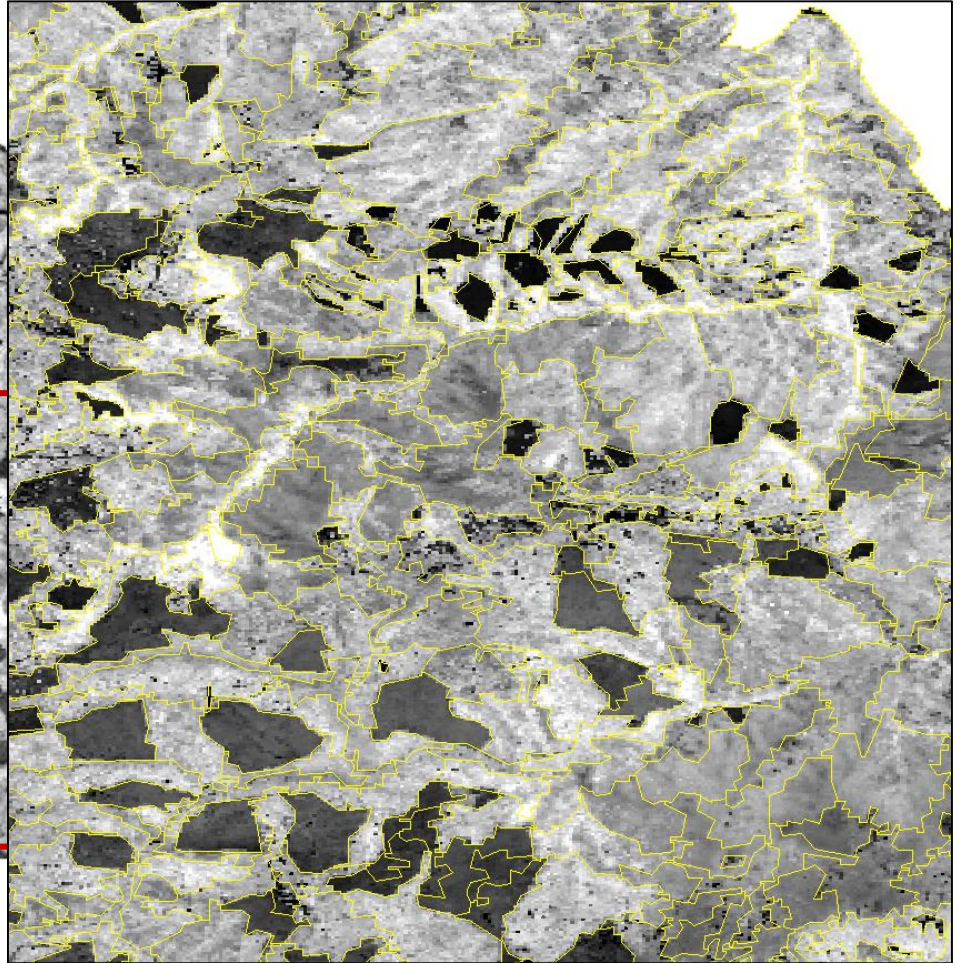
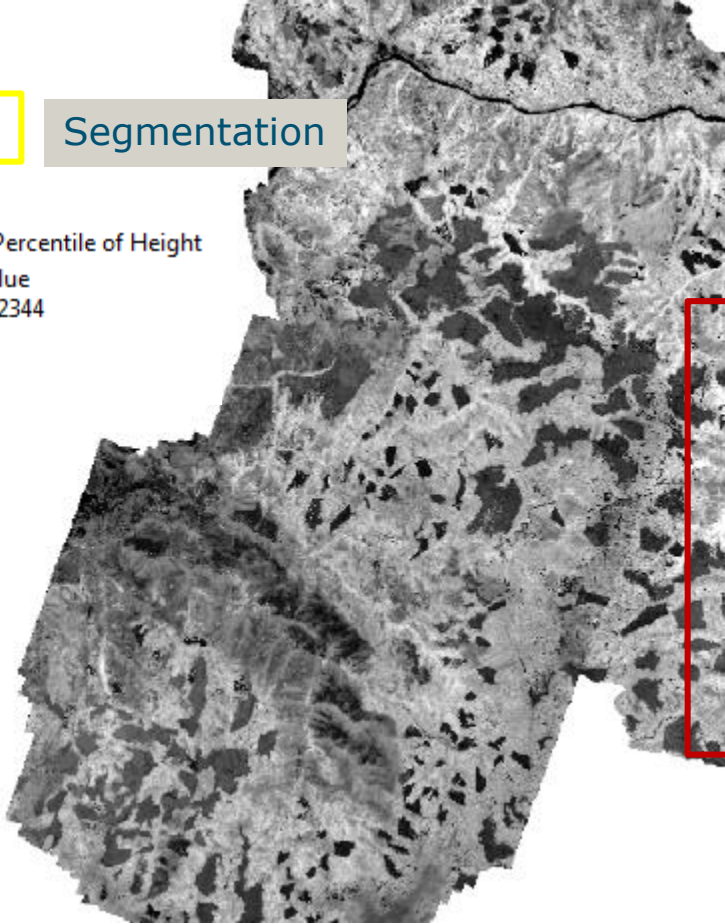




Segmentation

95 th Percentile of Height

Value
99.2344



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Segmentation

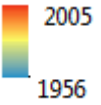
95 th Percentile of Height

Value
99.2344



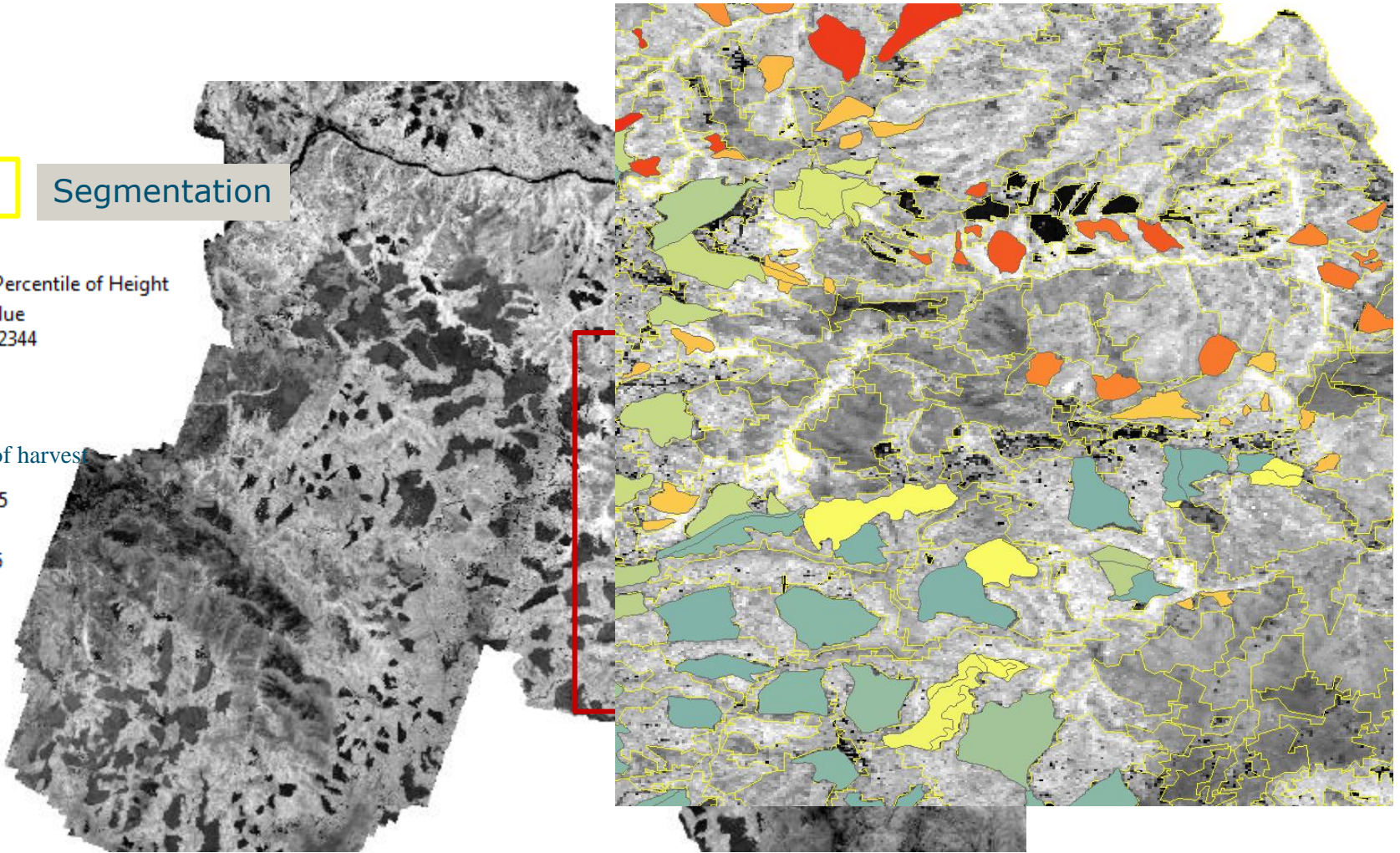
0

Year of harvest



2005

1956



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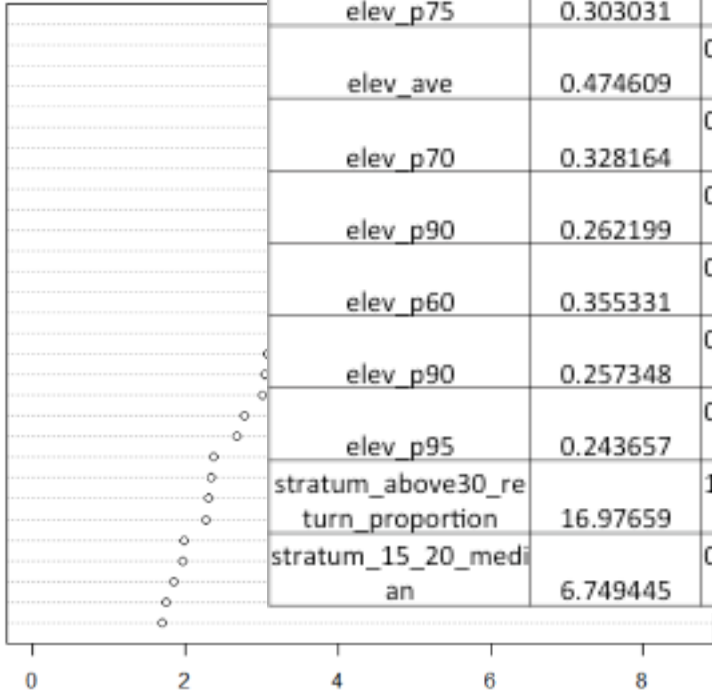


LiDAR classification: Disturbed/indisturbed

OOB estimate of
Confusion matrix:
change No change
change 302 1
No change 10 11

Metrics	Estimate	Std..Error	z.value	p-value	AIC	accuracy(tra ining)	accuracy(te sting)
stratum_above25_re turn_proportion	20.76967	2.287706	9.078819	1.10E-19	174.3443	0.891	0.909
elev_p80	0.281691	0.030303	9.295961	1.46E-20	176.0561	0.885	0.900
elev_p75	0.303031	0.032708	9.244525	2.36E-20	170.7109	0.894	0.891
elev_ave	0.474609	0.052788	8.990879	2.45E-19	157.3808	0.903	0.882
elev_p70	0.328164	0.035747	9.180101	4.31E-20	164.7914	0.903	0.882
elev_p90	0.262199	0.028969	9.051018	1.42E-19	180.3216	0.873	0.882
elev_p60	0.355331	0.038407	9.251617	2.21E-20	166.9559	0.903	0.873
elev_p90	0.257348	0.028422	9.054401	1.37E-19	184.6507	0.870	0.873
elev_p95	0.243657	0.027506	8.840953	9.49E-19	190.3655	0.864	0.873
stratum_above30_re turn_proportion	16.97659	1.886525	8.998869	2.28E-19	144.6348	0.906	0.873
stratum_15_20_medi an	6.749445	0.959271	7.036015	1.98E-12	190.1267	0.882	0.873

stratum_above25_return_proportion
stratum_above30_return_proportion
elev_p60_0p5plus_0p5
elev_p80_0p5plus_0p5
elev_quadratic_mean_0p5
elev_p50_0p5plus_0p5
elev_l1_0p5plus_0p5
elev_ave_0p5plus_0p5
stratum_20_25_max
stratum_20_25_return_proportion
stratum_15_20_median
elev_cubic_mean_0p5
elev_mad_median_0p5
elev_p75_0p5plus_0p5
stratum_15_20_mean
stratum_15_20_mode
stratum_20_25_cv
elev_p70_0p5plus_0p5
elev_mad_mode_0p5
stratum_above25_skewness
elev_p40_0p5plus_0p5
stratum_above25_kurtosis
stratum_20_30_max
stratum_20_30_median
elev_p90_0p5plus_0p5
elev_p99_0p5plus_0p5
elev_max_0p5plus_0p5
stratum_10_15_median
stratum_20_25_median
stratum_15_20_skewness

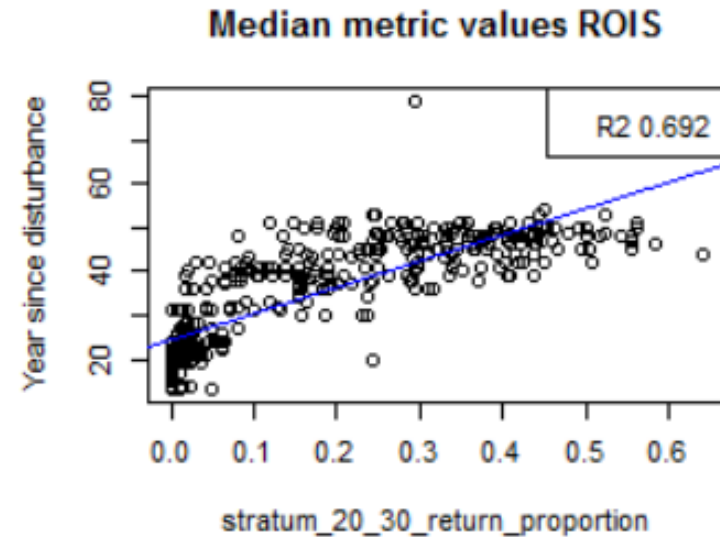
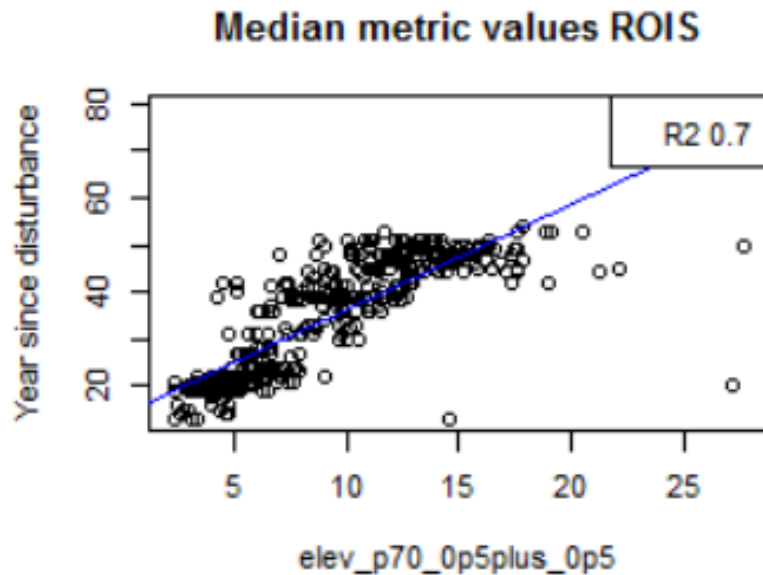


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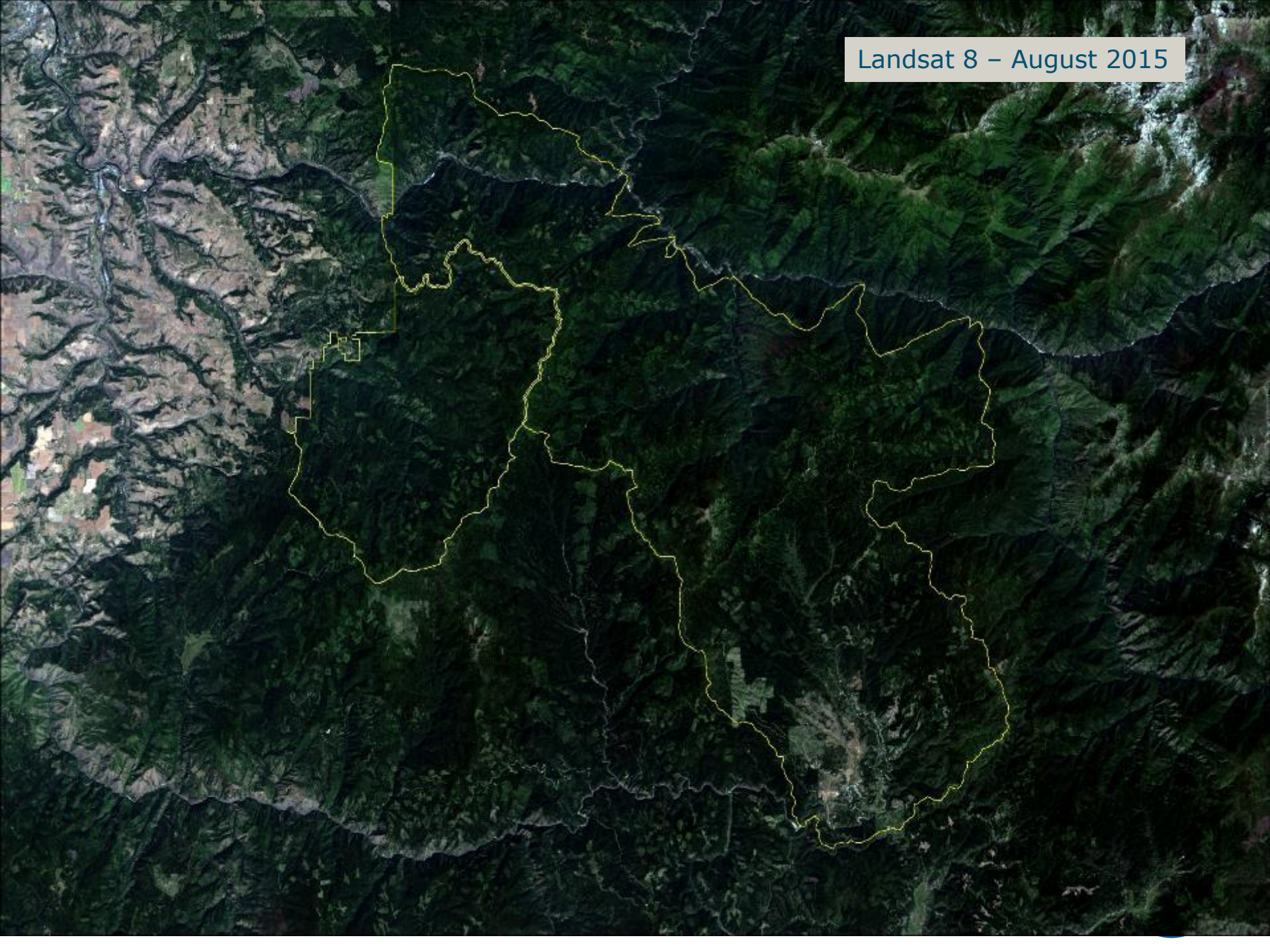
MeanDecreaseGini
University of Idaho
College of Natural Resources



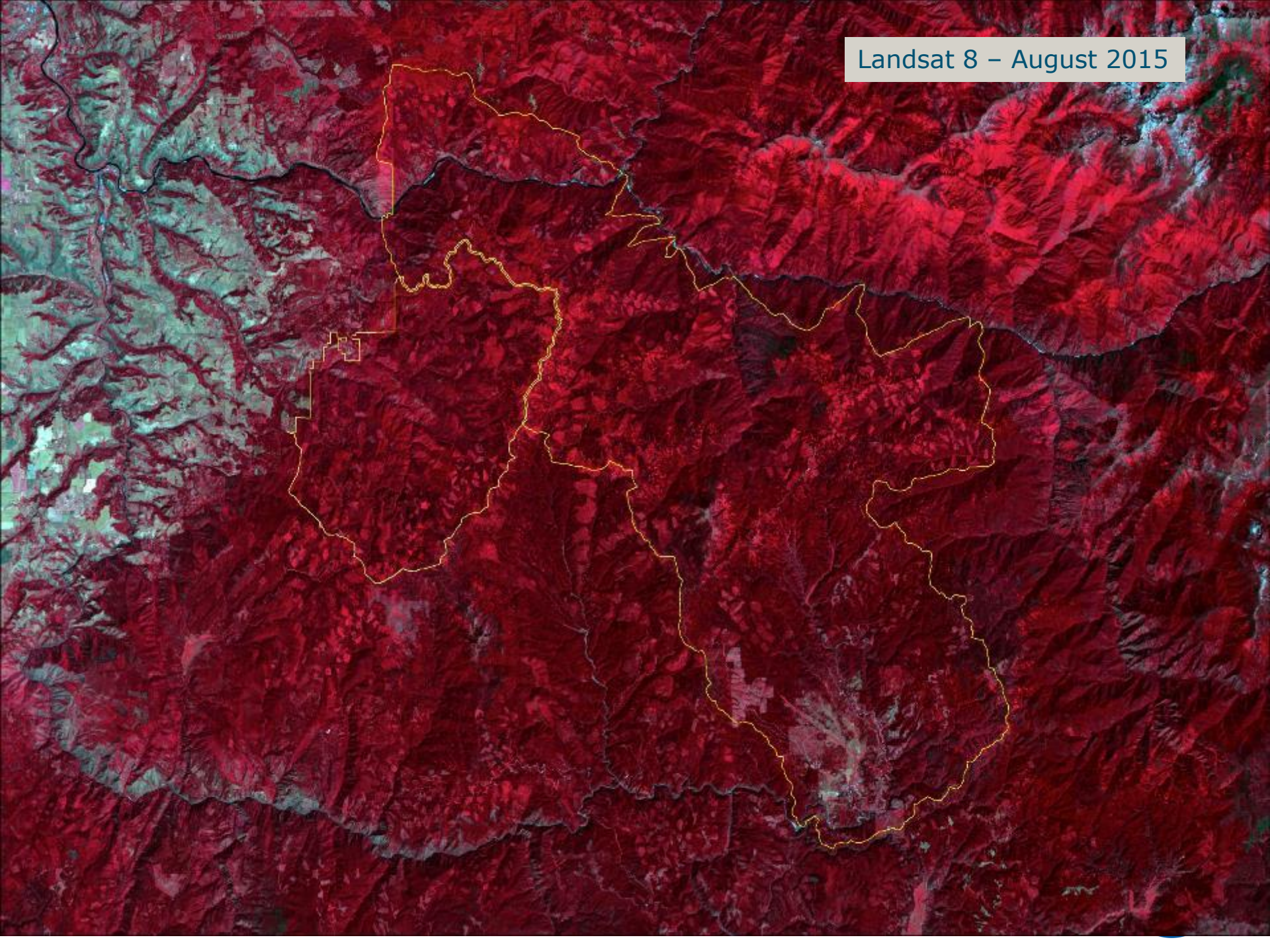
LiDAR analysis: time since disturbance



Landsat 8 - August 2015

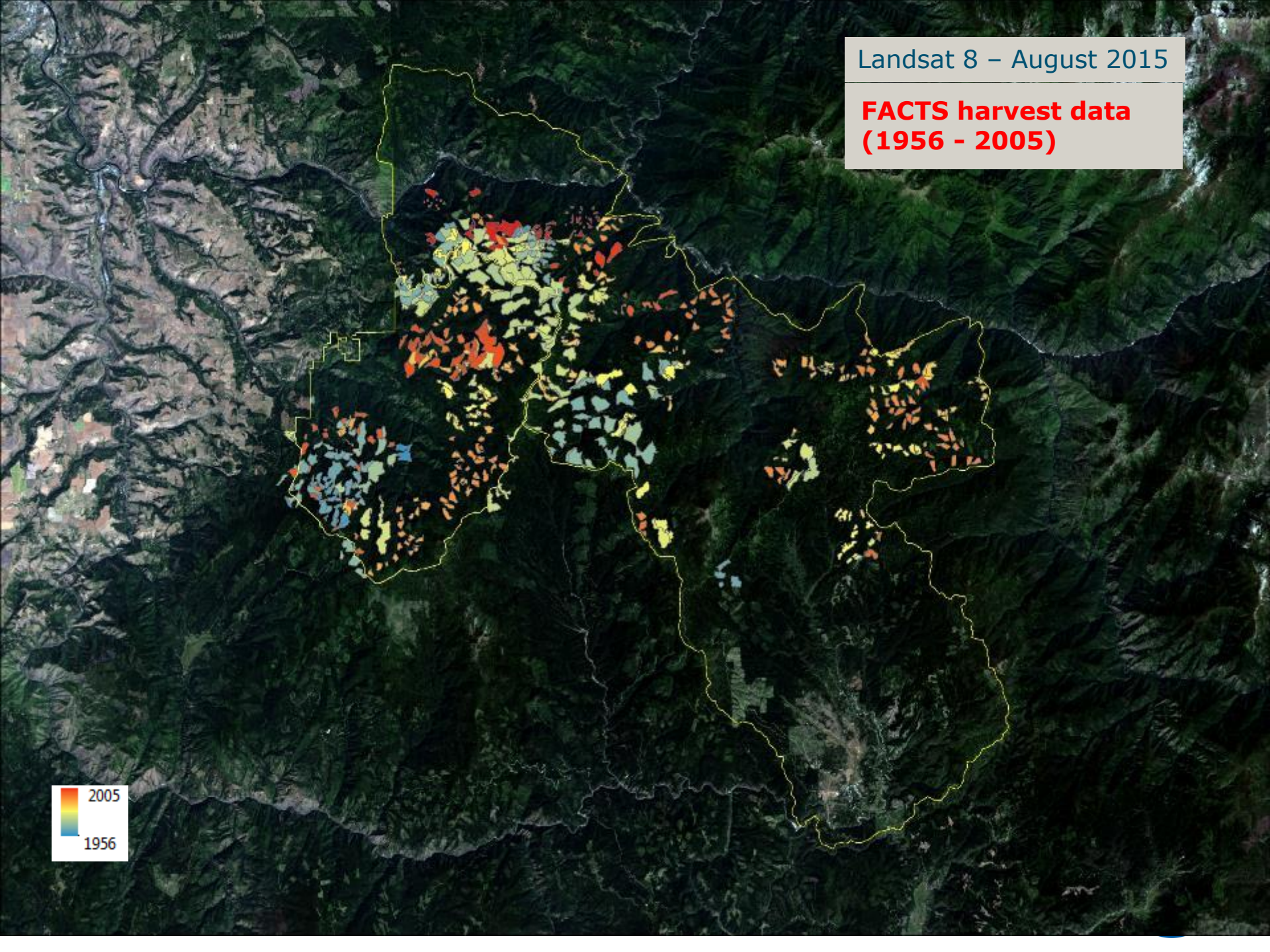
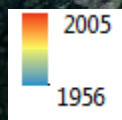


Landsat 8 - August 2015

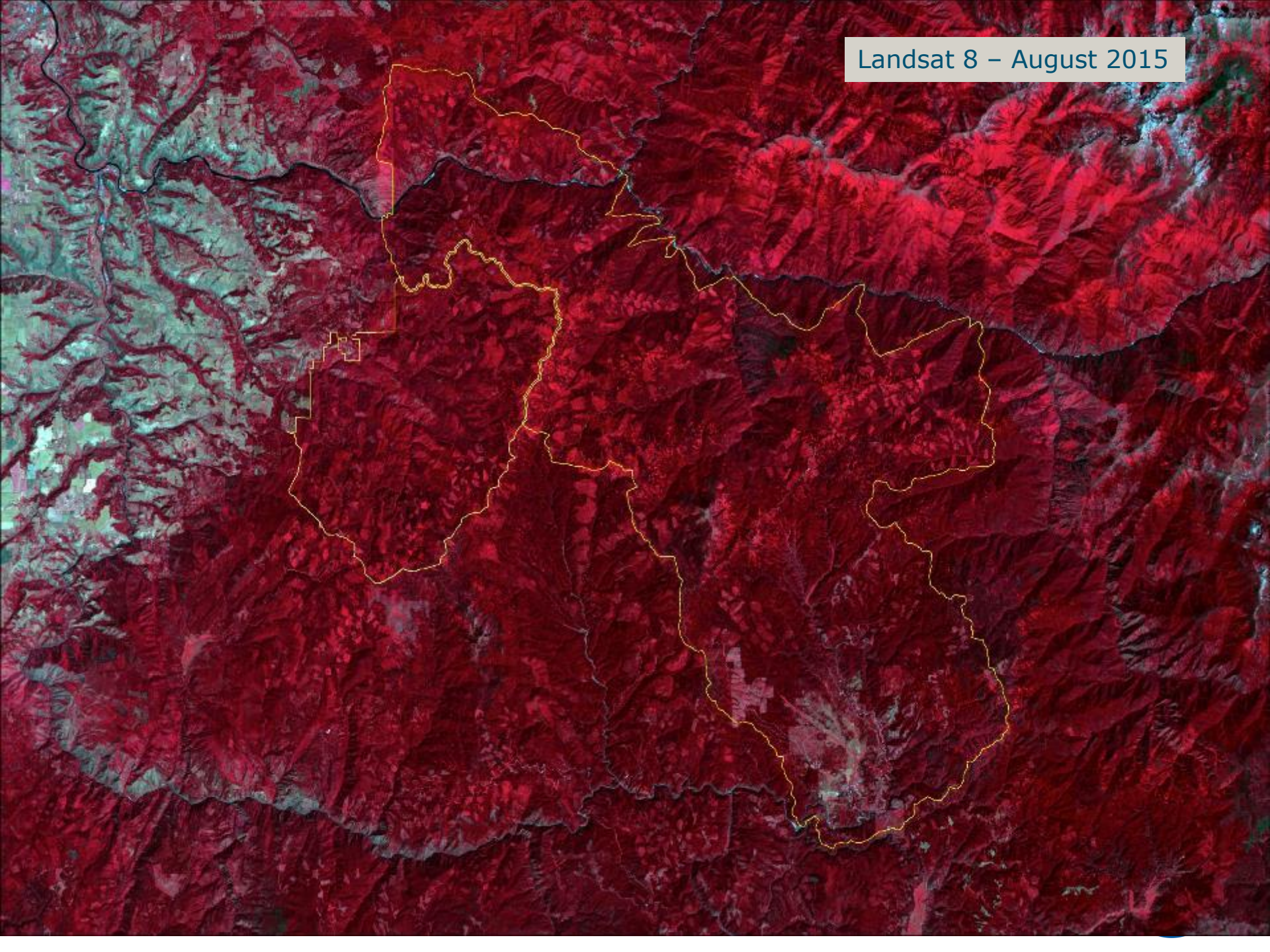


Landsat 8 - August 2015

**FACTS harvest data
(1956 - 2005)**

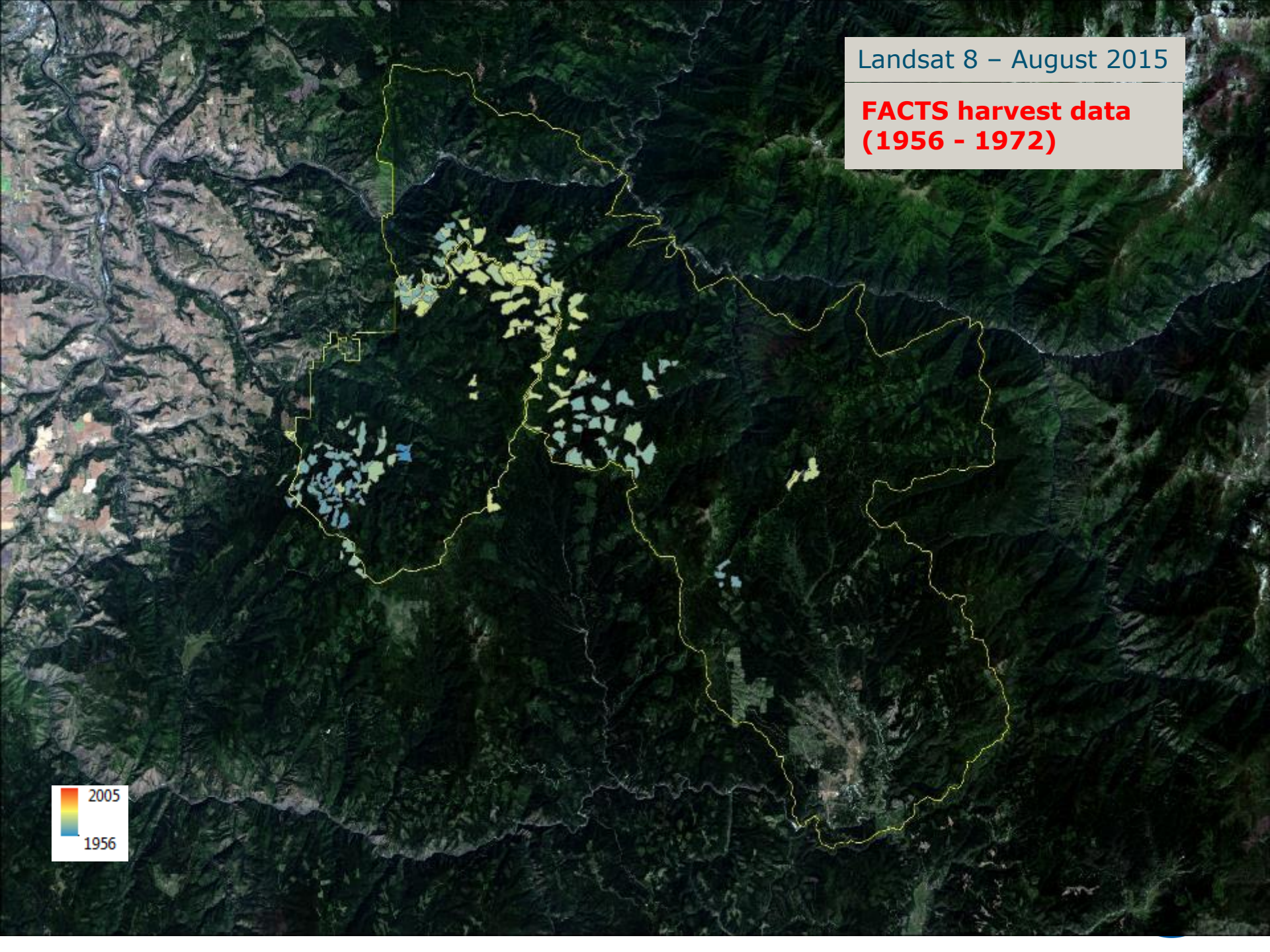
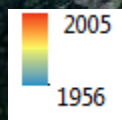


Landsat 8 - August 2015



Landsat 8 - August 2015

**FACTS harvest data
(1956 - 1972)**



What's next?

- LiDAR analysis:
 - Other disturbances (fire)
 - Data collection
 - Additional sites
- LiDAR – Landsat data fusion
 - Analysis of shapes and patterns from the 2004-2011 clearcuts
 - Potential for object oriented classification combining LiDAR metrics and vegetation indices
 - Waiting for L8 WELD

Comments, suggestions and criticism are
extremely welcome!

Industrial Forest Mapping
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Bonus slide: fire

